Chengdu Ebyte Electronic Technology Co.,Ltd

Wireless Modem

User Manual



ME31-AAAX4220
I/O Networking Module

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1. Product overview

1.1 Introduction



ME31-AAAX4220 is equipped with 2 channel A-type relay outputs and 2 channel analog inputs (0-20mA/4-20mA), and 4 channel dry contact input detection,supports Modbus TCP protocol or Modbus RTU protocol for acquisition and control and can be used as a simple Modbus gateway (automatically send commands with non-local Modbus addresses through the serial port/network port).

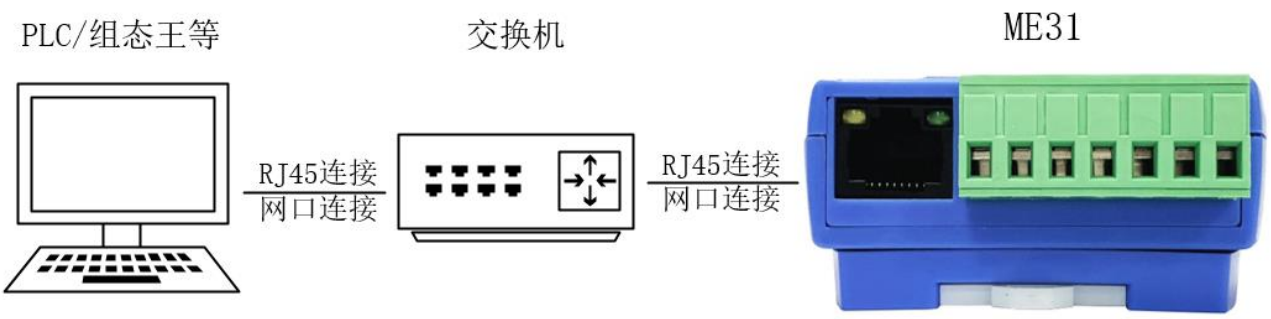
1.2 Features

- Good for standard Modbus RTU protocol and MODBUS TCP protocol;
- Work with various configuration software/PLC/touch screen；
- RS485 acquisition control I/O；
- RJ45 acquisition control I/O，support 4 channel master access；
- Support OLED display screen to display status information, and device parameters can be configured through buttons;
- 2 channel analog inputs（0-20mA/4-20mA）；
- 4-channel switch input DI (dry node) ；
- 2 channel switch output DO（A-type relay）；
- Switch output (DO) supports level mode, pulse mode, follow mode, reverse follow mode, and trigger flip mode;
- Support custom Modbus address settings；
- Support 8 common baud rate configurations ；
- DHCP and static IP；
- DNS function, domain name analysis；
- Support input output linkage.

1.3 Application typology diagram

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Network port application topology



Serial port application topology

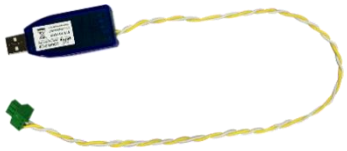
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2. Quick start

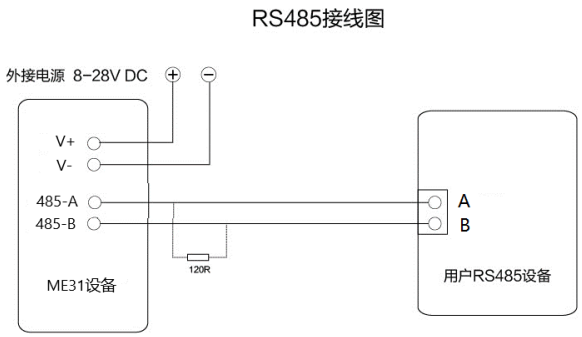
Note: The test need to carry out with factory parameter.

2.1 Devices required

		
ME31-AAAX4220	12V SMPS	USB to RS485
		
Computer	RJ45 Cable	More cables

2.2 Device connection

2.2.1 RS485 connection



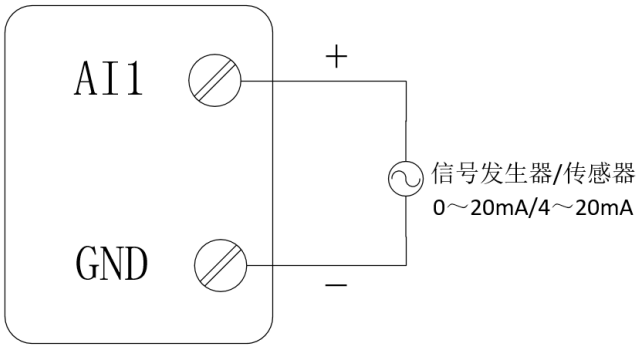
Note: When the 485 bus high frequency signal is transmitted, the signal wavelength is shorter than the transmission line, and the signal will form a reflected wave at the end of the transmission line, which will interfere with the original

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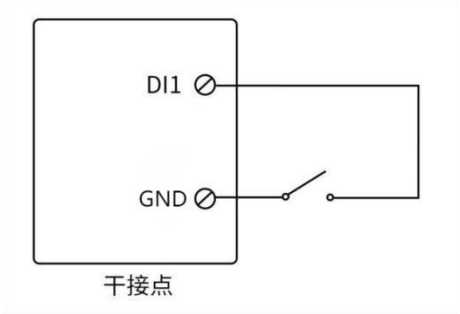
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signal. Therefore, a terminal resistance must be added at the end of the transmission line to prevent the signal from being reflected after reaching the end of the transmission line. The terminal resistance should be the same as the impedance of the communication cable, with a typical value of 120 ohms. Its function is to match the bus impedance and improve the anti-interference and reliability of data communication.

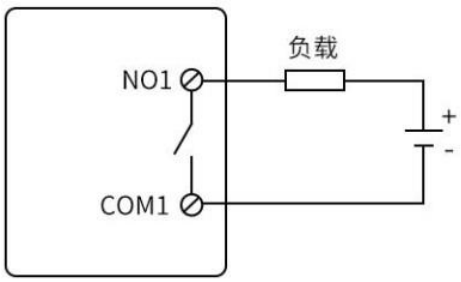
2.2.2 AI Analog input connection



2.2.3 DI Switching input connection



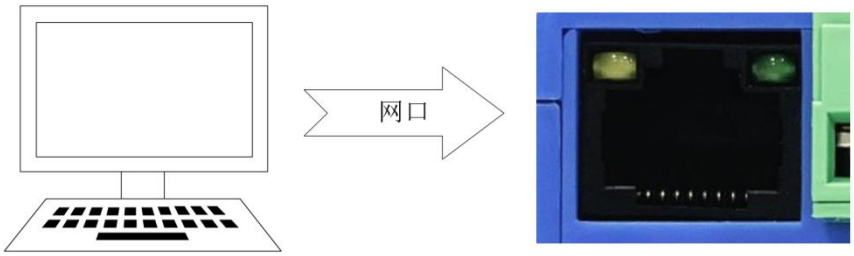
2.2.4 Relay output connection



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2.2.5 Simple use



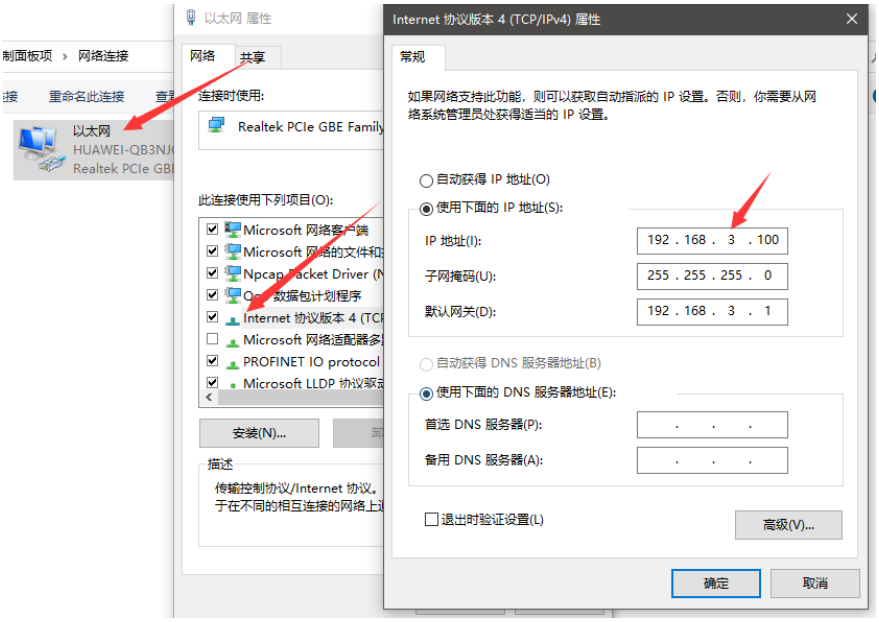
Wiring: The computer is connected to the RS485 interface of ME31-AAAX4220 through USB to RS485, A is connected to A, B is connected to B.

Networking: Insert the network cable into the RJ45 port and connect to the PC.

Power supply: Use DC-12V switching power supply (DC 8~28V) to supply power to ME31-AAAX4220.

2.3 Parameter configuration

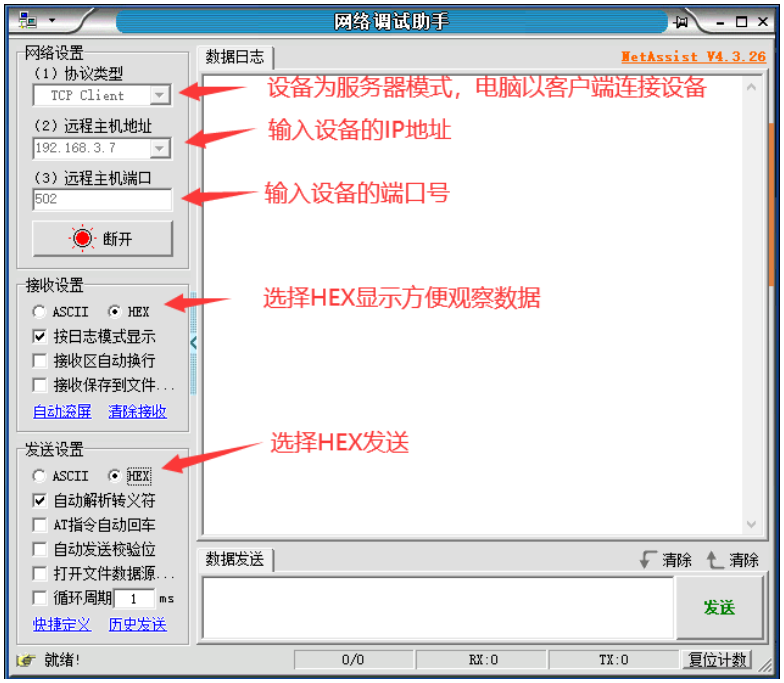
Step 1: Modify the IP address of the computer to be consistent with the device. Here it is modified to 192.168.3.100 to ensure the same network segment as the device and that the IP is different. Please turn off the firewall and try again if the step failed;



Step 2: Open the network assistant, select the TCP client, enter the remote host IP192.168.3.7 (default parameters), enter the port number 502 (default parameters), and select HEX to send.

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2.4 Control test

2.4.1 Modbus TCP Control

Use network assistant to control ME31-AAAX4220, first channel DO output.



To test other function according to below table

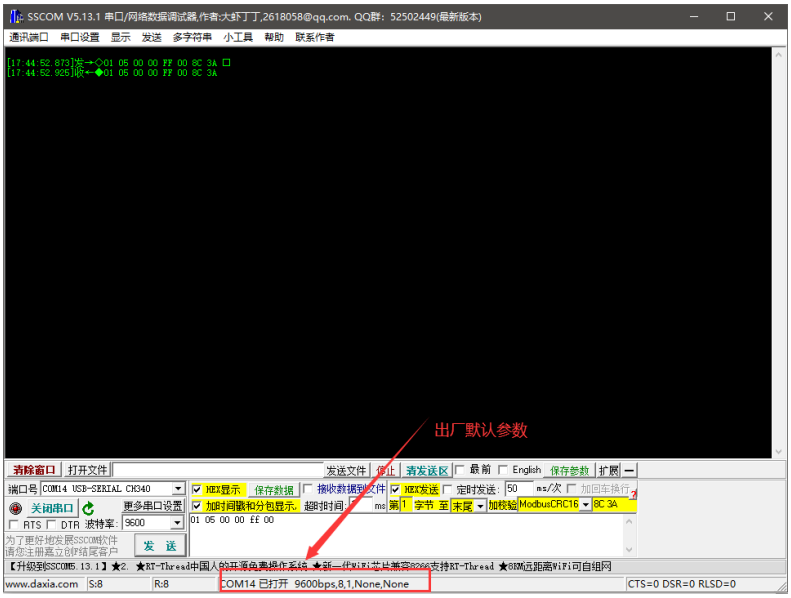
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Function （function code）	Command
Close the first route circle (0x05)	01 00 00 00 00 06 01 05 00 00 FF 00
Full open command (0x0F)	02 00 00 00 00 08 01 0F 00 00 00 02 01 03
Full close command (0x0F)	02 00 00 00 00 08 01 0F 00 00 00 02 01 00
Read all DI status (0x02)	01 00 00 00 00 06 01 02 00 00 00 04
Read all DO states (0x01)	01 00 00 00 00 06 01 01 00 00 00 02
Close the first route circle (0x05)	01 00 00 00 00 06 01 05 00 00 FF 00

2.4.2 Modbus RTU Control

Use network assistant to control ME31-AAAX4220, first channel DO output.



To test other function according to below table

Function （function code）	Command
Close the first route circle (0x05)	01 05 00 00 FF 00 8C 3A
Full open command (0x0F)	01 0F 00 00 00 02 01 03 9E 96
Full close command (0x0F)	01 0F 00 00 00 02 01 00 DE 97
Read all DI status (0x02)	01 02 00 00 00 04 79 C9
Read all DO states (0x01)	01 01 00 00 00 02 BD CB

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3 Technical indicator

3.1Specification and parameter

Category	Name	Parameter
Power supply	Operating voltage	DC8 ~ 28V
	Power indicator	Blue LED indicator
Serial port	Communication interface	RJ45、RS485
	Baud rate	9600bps（can be defined by user）
	Communication protocol	Standard Modbus TCP,Modbus RTU
MODBUS	Device address	Modify via Modbus command and computer
AI input	AI channels	2 channel
	Input type	0-20mA、4-20mA
	Acquisition frequency	10 Hz
	Input indicator	OLED display
	Acquisition properties	Single end input
	AI resolution	3‰
DO output	Number of DO channel	2 channel
	DO output type	A-type relay
	DO output mode	Level output, pulse output
	Relay contact capacity	30V/5A, 250V/5A
	Output indication	OLED screen display, red LED indication
Others	Product size	121mm * 72mm * 34mm
	Product weight	145 ±5 g
	Working temperature and humidity	-40 ~ +85℃、5% ~ 95%RH（no condensation ）
	Storage temperature and humidity	-40 ~ +105℃、5% ~ 95%RH（no condensation ）
	Installation	Din rail installation

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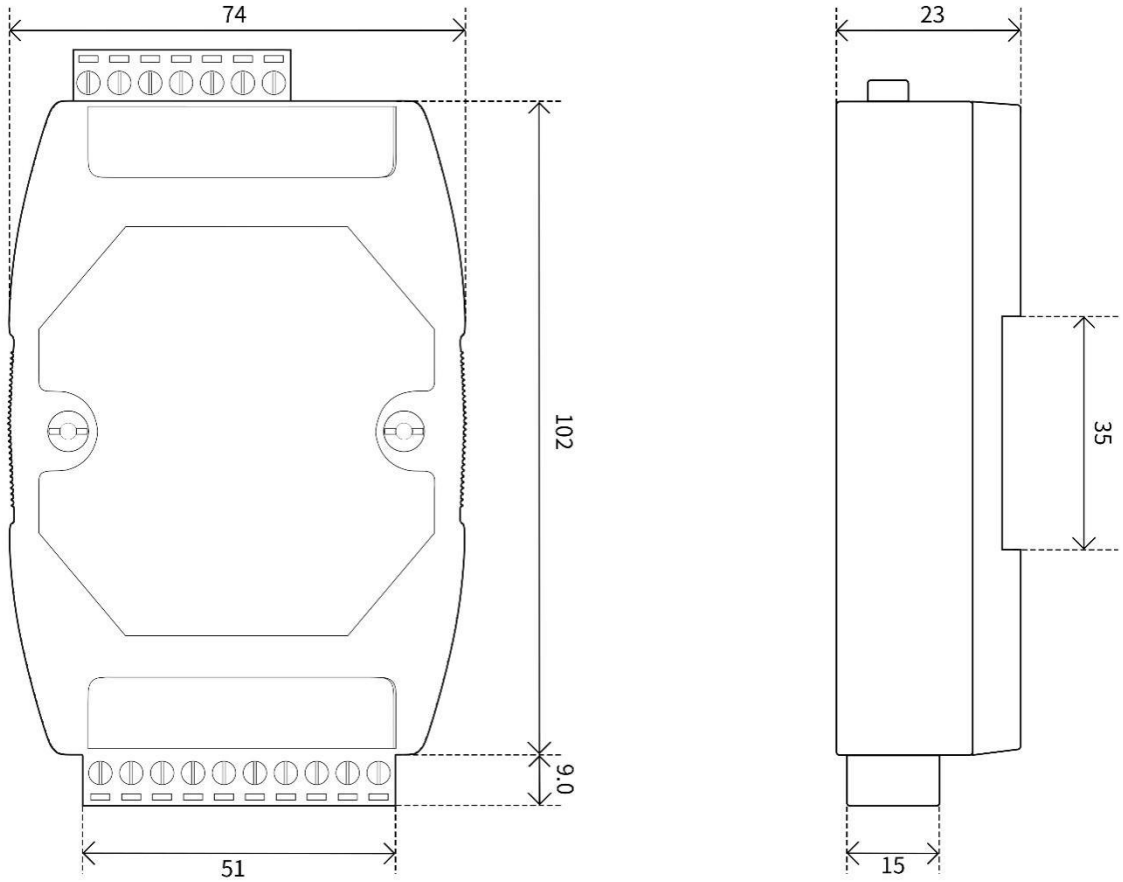
3.2 Device default parameter

Category	Name	Parameter
Ethernet parameter	Working mode	TCP server（Max 4 channel client access）
	Local IP	192.168.3.7
	Local port	502
	Subnet mask	255.255.255.0
	Gateway address	192.168.3.1
	DHCP	Off
	Local MAC	Depending on chip（fixed）
	Target IP	192.168.3.3
	Target port	502
	DNS server	114.114.114.114
	Active upload	Off
UART parameter	Baud rate	9600bps（8 type）
	Check method	None（default）、Odd、Even
	Data bit	8
	Stop bit	1
MODBUS parameter	Modbus master slave	Slave
	Address	1

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3.3 Dimensions



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3.4 Ports and indicators



No.	Sticker	Remarks
1	TX（LED）	UART TX data
2	RX（LED）	UART RX data
3	LINK（LED）	Network link
4	NET（LED）	Network data TX and RX
5	PWR（LED）	Power input
6	DI1（LED）	Switch input indicator of channel 1
7	DI2（LED）	Switch input indicator of channel 2
8	DI3（LED）	Switch input indicator of channel 3
9	DI4（LED）	Switch input indicator of channel 4
10	DO1（LED）	First relay output indicator light
11	DO2（LED）	Second relay output indicator light
12	GND	Negative pole of power input terminal, DC 8V~28V, 5.08mm Phoenix terminal.
13	VCC	Positive pole of power input terminal, DC 8V~28V, 5.08mm Phoenix terminal.
14	AI1	Analog input channel 1, supporting 0 to 20mA current input, 5.08mm Phoenix terminal.

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15	GND	Channel 1 analog input ground, DC 8V~28V, 5.08mm Phoenix terminal.
16	AI2	Analog input channel 2, supporting 0 to 20mA current input, 5.08mm Phoenix terminal.
17	GND	Channel 2 analog input ground, DC 8V~28V, 5.08mm Phoenix terminal.
18	NO1	Relay 1 normally open pin, used in conjunction with relay 1 common terminal, 5.08mm Phoenix terminal.
19	COM1	Relay 1 common terminal, used in conjunction with relay 1 normally open pin, 5.08mm Phoenix terminal.
20	NO2	Relay 2 normally open pin, used in conjunction with relay 2 common terminal, 5.08mm Phoenix terminal.
21	COM2	Relay 2 common terminal, used in conjunction with relay 2 normally open pin, 5.08mm Phoenix terminal.
22	Ethernet	Ethernet interface, standard RJ45 interface.
23	DI4	Switching input channel 4, supporting dry contact connection, 5.08mm Phoenix terminal.
24	DI3	Switching input channel 3, supporting dry contact connection, 5.08mm Phoenix terminal.
25	DI2	Switching input channel 2, supporting dry contact connection, 5.08mm Phoenix terminal.
26	DI1	Switching input channel 1, supporting dry contact connection, 5.08mm Phoenix terminal.
27	GND	Channel 1-4 switch input ground, 5.08mm Phoenix terminal.
28	485-A	The serial port A is connected to the external device A interface, with a 5.08mm Phoenix terminal.
29	485-B	The serial port B is connected to the external device B interface, with a 5.08mm Phoenix terminal.

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4 Product function introduction

4.1DI input

4.1.1Switch input DI acquisition

Switch input DI measurement level signal or edge pulse signal (rising edge, falling edge). Support dry node collection, support DI counting function, the maximum count is 65535 (the count is automatically cleared if it exceeds 65535).

The switch input DI branch has three trigger modes: rising edge, falling edge and level (default rising edge trigger).

The clearing method supports automatic clearing and manual clearing (default automatic clearing).

4.1.2 Input filtering

When the switch input DI collects the signal, it needs to keep several sampling cycles before confirming. Filter parameters can be set in the range of 1 to 16 (default 6 sampling periods, 6*1kHz).

It can be configured with the host computer through instructions.

4.2 AI input

4.2.1 Analog range

Analog input AI measurement current signal, with a collection range of 0-20mA or 4-20mA, an accuracy of 3 ‰, and a resolution of 12 bits. Adopting single ended input, sampling frequency 10Hz, input impedance 100 Ω.

Set the sampling range for all AI channels, with valid values of 1 and 0 (default 0).

Configuration is 0: represents 0-20mA

Configuration is 1: represents 4-20mA

[Note] AI Configuration Description

(1) The AI sampling range for each channel can be set. When the AI channel sampling range is configured to 4-20mA sampling, 0 is displayed if the current signal is below 3.5mA, and 4 is displayed if it is above 3.5mA and below 4mA. There is no conversion limit for signals greater than 20mA, but it cannot exceed 25mA (exceeding 25mA may pose a risk of equipment damage).

(2) The starting address of the AI channel sampling range parameter is 0x04B2, the register type is holding register, and the function codes are 0x06 and 0x10. When writing the AI channel sampling range parameter, if the written parameter value is not within the range of 0-1, the closest value will be automatically taken for writing. If the writing sampling range parameter is 2, the device takes 1 as the sampling range parameter, and Modbus does not return an error command.

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4.2.2 Trigger mode

(1) Not triggered: mode off.

(2) Rising Trigger: When the AI input value becomes greater than the set AI trigger high value, a rising edge trigger occurs, changing the state of the DO. For the rising edge trigger to change the DO state again, the AI input value must be lower than the set AI trigger low value for the rising edge trigger to take effect again (the DO working mode needs to be set to trigger flip mode).

(3) Falling Trigger: When the AI input value becomes lower than the set AI trigger high value, a falling edge trigger occurs, changing the state of the DO. For the falling edge trigger to change the DO state again, the AI input value must be higher than the set AI trigger high value for the falling edge trigger to take effect again (the DO working mode needs to be set to trigger flip mode).

(4) Dual-Edge Trigger: When the AI input value becomes greater than the set AI trigger high value, the AI trigger becomes high (i.e., the DO output state changes once), generating a rising edge trigger. After triggering, as long as the AI value does not drop below the set AI trigger low value, the current DO output value remains unchanged. When the AI input value becomes lower than the set AI trigger low value, the AI trigger becomes low (i.e., the DO output state changes once), generating a falling edge trigger. After triggering, as long as the AI value does not exceed the set AI trigger high value, the current DO output value remains unchanged (the DO working mode needs to be set to trigger flip mode).

4.2.3Analog input engineering quantity shaping value, engineering quantity floating point value

There are two ways to read the current signal size collected by the device:

(1) Read the AI engineering quantity shaping value and directly convert it to obtain the input current. The starting address of the AI engineering quantity shaping value register is 0x0064, the register type is input register, and the read function code is 0x04. This method returns a register representing one channel and reads values ranging from 0 to 25000. The method for calculating the current size is 0-25000 corresponding to 0-25A. Namely:

Current=engineering quantity value/1000 (mA)

(2) Read the floating point value of AI engineering quantity, and use IEE754 conversion tool to convert hexadecimal data to Floating-point arithmetic to get the input current. The starting address of the AI engineering quantity shaping value register is 0x00C8, the register type is input register, and the read function code is 0x04. This method returns two registers representing one channel.

4.2.4 AI Filter parameters

The filtering parameters of the AI channel can be set, with valid values ranging from 1 to 16 and a default value of 6. Filter parameter description:

(1) All AI channels share a common filtering parameter, and the higher the parameter value, the more stable the output value, and the slower the response.

(2) The AI channel filtering parameter address is 0x04B0, and the register type is a holding register. Function codes 0x06 and 0x10.

(3) When writing AI filtering parameters, if the parameter values written are not within the range of 1-16, the closest

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value will be automatically taken for writing. If the filtering parameter is written as 0, the device will take 1 as the filtering parameter, and Modbus will not return error instructions.

4.3 DO output

The output mode of the relay outputs different modes based on the user set mode, with the default level output turned on.

4.3.1 Input Count

Supports counting of DI inputs, and users can configure it for rising edge acquisition, falling edge acquisition, and level acquisition according to their own needs. You can also change the reset method according to your needs.

Trigger method:

Rising edge: Collect the rising edge (without counting on conduction, counting on shutdown) and count once.

Falling edge: Collect the falling edge (counted when conducting, not when releasing) and count once.

Level: Collect two edges and count them separately.

Zeroing method:

Automatic: The device will automatically reset every time the DI count value register (0x09DF~0x09E6) is read.

Manual: The manual mode requires a write 1 operation on the reset signal registers (0x0AA7~0x0AAE), with each holding register controlling one reset signal.

4.3.2 Level Output

According to the level set by the user, the switch characteristic of the level mode is similar to the function of a self-locking switch.

4.3.3 Pulse output

After the switch output DO is turned on, the switch output DO is automatically turned off after maintaining the set pulse width time (in ms). The pulse width setting range is 50~65535ms (50ms by default).

4.3.4 Follow mode

According to the following source configured by the user (when the device has AI acquisition or DI detection function, DI or AI can be used as the following source, otherwise this function is useless) to change the relay state, multiple outputs can follow the same follow source output, simply DI When the input is detected, the relay is automatically output as the following source (for example: DI is 1, DO is closed). When the follow mode is turned on, the follow source should be configured at the same time, otherwise it will follow the first input by default.

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4.3.5 Reverse follow mode

According to the following source configured by the user (when the device has AI acquisition or DI detection function, DI or AI can be used as the following source, otherwise this function is useless) to change the relay state, multiple outputs can follow the same follow source output, simply DI When the input is detected, the relay is automatically output as the following source (for example: DI is 1, DO is disconnected). When the follow mode is turned on, the follow source should be configured at the same time, otherwise it will follow the first input by default.

4.3.6 Trigger flip mode

According to the following source configured by the user (when the device is equipped with AI acquisition or DI detection function, DI or AI can be used as the following source, otherwise this function is useless) to change the relay state, multiple outputs can follow the same follow source output, simply speaking, when When DI generates a trigger signal (rising edge or falling edge), DO will have a state change. When the trigger flip mode is turned on, the following source should be configured at the same time, otherwise it will follow the first input by default.

4.3.7 Power-on state

According to the state set by the user. After the device is powered on, the output relay is turned on according to the state set by the user, and it is turned off by default.

4.4 Modbus gateway

The device can transmit non local Modbus instructions from the network/serial port to the serial port/network, and the local Modbus instructions can be executed directly.

4.4.1 Modbus TCP/RTU Protocol Conversion

After being turned on, the Modbus TCP data on the network side will be converted into Modbus RTU data.

4.4.2 Modbus address filtering

This function can be used in certain host software or configuration screens as the host to access the device serial port, and the gateway function of the device is used. When the slave is on the network side and the Modbus TCP to RTU function is enabled, the presence of multiple slaves on the bus may cause data confusion. At this time, enabling address filtering can ensure that only the specified address can pass through the device; When the parameter is 0, data is transmitted through, and when the parameter is 1-255, data is only transmitted through the set slave address.

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4.4.3 Modbus TCP protocol data frame description

TCP frame format：

Transaction ID	Protocol ID	Length	Device Address	Function Code	Data Segment
2 Bit	2 Bit	N+2 Bit	1 Bit	1 Bit	N Bit

- Transaction identification: It can be understood as the serial number of the message. Generally, 1 is added after each communication to distinguish different communication data messages.
- Protocol identifier: 00 00 means Modbus TCP protocol.
- Length: Indicates the next data length, in bytes.

For example：get DI state

01 00	00 00	00 06	01	02	00 00 00 04
Transaction ID	Protocol ID	Length	Device Address	Function Code	Data Segment

4.4.4 Modbus RTU protocol data frame description

RTU frame format：

Device Address	Function Code	Data Segment	Check code CRC
1 Bit	1 Bit	N Bit	2 Bit

For example：get DI state command

01	02	00 00 00 04	79 C9
Device Modbus address	Function Code	Data Segment	CRC check code

4.5 IO Linkage function

The linkage function is divided into AI-DO linkage and DI-DO linkage
Generally speaking, the linkage function needs to be divided into two parts.
The first part is the trigger source: both AI/DI input, the second part is the trigger: both DO/AO output
1. When DI is used as the trigger source, DI input status and DI changes can be used as signals, according to the corresponding configuration of DO
a. In the following/reverse following mode, the current state of DI will be used as a signal, and the state of DO is the same/opposite to that of DI
b. Trigger inversion mode, DI state change is used as a signal, if the trigger signal is set to DI rising edge change, the current state of DO will change once
2. When AI is used as the trigger source, the AI signal is processed into a signal similar to DI through a process similar to Schmitt trigger (refer to Chapter 4.2.2), and then this signal is linked with DO. The linkage process can

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refer to DI/DO linkage.

4.6 Active upload

The device supports the function of uploading analog input values at fixed time intervals. Setting the value of the corresponding register can control the interval time and whether to upload or not.

The device with digital input will actively upload once after connecting to the server successfully, and then the digital input will be uploaded following the status change, and the device with analog input will report the status of the analog input according to the configuration of the active upload time period (the configuration period is 1-65535).

When set to 0, the upload is closed, and when set to another positive integer value N, the upload is performed at intervals of N seconds.

[Note] The device can only be valid if it is in the client mode configuration. If the register value is non-zero, active uploading is enabled.

4.7 Custom Module Information

4.7.1 Modbus address

The default address of the device is 1, and the address can be modified. The address range is 1-247.

4.7.2 Module name

Users can configure the device name for differentiation according to their own needs. It supports English and digital formats, and the maximum length is 20 bytes.

4.7.3 Network parameter

Unless otherwise specified: The following network-related parameters default to IPV4-related parameters.

(1) MAC of the device: the user can obtain it by reading the specified register, and this parameter cannot be written.

(2) IP address: IP address of the device, readable and writable.

(3) Modbus TCP port: the port number of the device, readable and writable.

(4) Subnet mask: address mask, readable and writable.

(5) Gateway address: gateway.

(6)DHCP: Set the way the device obtains IP, static (0), dynamic (1).

(7)Target IP: When the device works in client mode, the target IP or domain name of the device connection.

(8)Target port: When the device works in client mode, the target port to which the device is connected.

(9)DNS server: When the device is in client mode, it resolves the server domain name.

(10)Module working mode: switch the working mode of the module. Server: The device is equivalent to a server, waiting for the user's client to connect, and the maximum number of connections is 4. Client: The device actively

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connects to the target IP and port set by the user.

(11)Active upload: When the secondary parameter is not 0 and the device is in the client mode, the discrete input state of the device will be uploaded to the server after the initial connection or input changes, and the analog input will be uploaded according to the configured time period.

4.7.4 UART parameter

Parameters for setting serial communication:
Default parameters:
Baud rate: 9600(03);
Data bits: 8bit;
Stop bit: 1bit;
Check digit: NONE(00);

(1) Baud rate：

Baud rate code value table	
0x0000	1200
0x0001	2400
0x0002	4800
0x0003（default）	9600
0x0004	19200
0x0005	38400
0x0006	57600
0x0007	115200

(2) Check digit：

Check digit	
0x0000(default)	NONE
0x0001	ODD
0x0002	EVEN

4.8 OLED display and parameter configuration

The display interface includes information display page (AI input and DI input status, DO output status) and parameter setting page (part of parameters).

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4.8.1 Information display interface

Including the current input value display page, shortly press the left and right buttons to switch the interface

4.8.2 Device parameter display interface

Press the left or right button to enter the password input interface, complete the correct password input, and display the device parameter information interface (password interface: default password: 0000; short press the middle verification password, left and right buttons to switch password bits, up and down buttons to switch current bit values, a total of 4 digits of the password, with each input range of 0-9 digits):

The parameter setting interface from top to bottom is

1. :Modbus address;
2. Baud rate;
3. Data bits;
4. Check digit;
5. Stop bit;
6. Local port
7. Local IP address
8. Network mode
9. Gateway
10. Subnet mask
11. DNS
12. MAC address
13. DHCP
14. Target IP
15. Target port
16. Modbus TCP/RTU protocol conversion
17. Active upload
18. Modbus address filtering

4.8.3 Device parameter configuration interface

Long press the confirm button to enter the password input interface, complete the correct password input, and enter the configuration interface (password interface: default password: 0000; short press the middle to verify the password, left and right buttons to switch password bits, up and down buttons to switch current bit values, a total of 4 digits of password, with each digit entering a range of 0-9 numbers).

Select the setting option, enter the parameter configuration page, and briefly press the up and down keys to switch between the setting options;

Select the setting item, short press to confirm or right-click, and the cursor for the setting item represents the selected item and enters the setting item;

Adjust parameter values: After selecting the setting option, the up and down keys can change the numerical value or optional values; Press the left and right buttons to move the cursor within the parameter item;

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Confirm parameter values: After adjusting the parameter values, press the confirm button to exit the current setting.

Save parameter settings and restart: After setting the parameters, move the cursor to save and restart, then short press the confirm button to enter the confirm save and restart state. Short press the confirm button (press other buttons to exit the confirmation state) to save the parameters and restart the device.

Exit without saving parameters: move the cursor to Exit, and then press the OK key briefly to enter the confirmed Exit status. Press the OK key briefly (press other keys to exit the confirmed status) to exit the parameter configuration interface without saving parameters.

Among them, the data bits and stop bits cannot be set. After enabling DHCP mode, the local IP address, gateway, and subnet mask cannot be configured and only assigned by the router;

4.8.4 Screen sleep

The device screen has a sleep function, which is turned off by default and can be set to turn on in the configuration interface.

In any interface, after 180 seconds of no button operation, the screen will enter sleep mode, and the interface will display Xiaoyi Robot. Press any button to exit sleep mode.

When the screen is dormant, the efficiency of device program operation will be improved.

4.9 MODBUS parameter setting

Note: According to the usage requirements, some software (such as KingView) requires adding +1 when converting from hexadecimal to decimal in order to operate on registers (all decimal values in the table have already been adjusted by +1).

4.9.1 DI register list

Register function	Register address (HEX)	Register address (DEC)	Register type	Quantity	Operation	Data Range/Remarks	Related function codes
DI state	0x0000	1-0001	Discrete input	4	R	Enter the port state	R：0x02
DI filter parameters	0x04B1	4-1202	Holding register	1	RW	Digital filter parameter, the range is 1~16, the smaller the number, the more sensitive, the larger the more stable, the default is 6	R：0x03 W：0x06、0x10
DI pulse count value	0x09DF	4-2528	Holding register	4	RW	Enter count value	R：0x03 W：0x06、0x10
DI clear way	0x0A43	4-2628	Holding register	4	RW	0x0000 auto clear 0x0001 manual clear	R：0x03 W：0x06、0x10

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DI manual clear signal	0xAA7	4-2728	Holding register	4	RW	The clearing method is manual, and the register writes 1 to clear the count value	R：0x03 W：0x06、0x10
DI count way	0x0B0C	4-2829	Holding register	4	RW	Set DI count way	R：0x03 W：0x06、0x10

4.9.2 AI register list

Register function	Register address (HEX)	Register address (DEC)	Register type	Quantity	Operation	Data Range/Remarks	Related function codes
Integer value of AI engineering quantity	0x0064	3-0101	input register	2	R	16-bit integer type, unit uA	R：0x04
Floating point value of AI engineering quantity	0x00C8	3-201	input register	4	R	32-bit floating point type, unit mA	R：0x04
AI filter parameters	0x04B0	4-1201	holding register	1	RW	Analog input filter parameters, range 1-16, the smaller the number, the more sensitive, the larger the more stable, default 6	R：0x03 W：0x06、0x10
AI sampling range	0x04B2	4-1203	holding register	2	RW	AI channel sampling range	R：0x03 W：0x06、0x10
AI Trigger High Value	0x1F40	4-8001	holding register	2	RW	0x0000: 0~20mA	R：0x03 W：0x06、0x10
AI Trigger Low Value	0x1F72	4-8051	holding register	2	RW	0x0001: 4-20mA	R：0x03 W：0x06、0x10
AI trigger mode	0x1FA4	4-8101	holding register	2	RW	0-20000(uA)	R：0x03 W：0x06、0x10

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4.9.3 DO register list

Register function	Register address (HEX)	Register address (DEC)	Register type	Quantity	Operation	Data Range/Remarks	Related function codes
DO state	0x0000	0-0001	Coil	2	RW	Write to change the current DO state, read to get the current DO state	R：0x01 W：0x0F、0x05
DO power-on state	0x0064	4-0101	holding register	2	RW	The default state of the coil after power-on	R：0x01 W：0x0F、0x05
DO work mode	0x0578	4-1401	holding register	2	RW	0x0000 level without following mode	R：0x03 W：0x06、0x10
DO pulse width	0x05DC	4-1501	holding register	2	RW	0x0001 pulse without following mode	R：0x03 W：0x06、0x10
DO follow source	DI:0x0000 AI:0x8000	DI:4-0001 AI:4-32769	holding register	2	RW	0x0002 follow mode	R：0x03 W：0x06、0x10

4.9.4 Module related register

Register function	Register address (HEX)	Register address (DEC)	Register type	Quantity	Operation	Data Range/Remarks	Related function codes
Module address	0x07E8	4-2025	Holding register	1	RW	Modbus address， 1～247 configurable	R：0x03 W：0x06
Module model	0x07D0	4-2001	Holding register	12	R	Get current model	R：0x03
Firmware version	0x07DC	4-2013	Holding register	1	R	Get firmware version	R：0x03
Module name	0x07DE	4-2015	Holding register	10	RW	Define module name	R：0x03 W：0x10
Module reset	0x07EA	4-2027	Holding register	1	W	Write 0x5BB5 to reboot.	W：0x06
Restore factory parameter	0x07E9	4-2026	Holding register	1	W	Write 0x5BB5 to restore factory settings.	W：0x06
Serial baud rate	0x0834	4-2101	Holding register	1	RW	See the baud rate code table， Default 9600（0x0003）	R：0x03 W：0x06、0x10
Serial check digit	0x0836	4-2103	Holding register	1	RW	0x0000 none（default） 0x0001 odd 0x0002 even	R：0x03 W：0x06、0x10

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4.9.5 Network related register

Register function	Register address (HEX)	Register address (DEC)	Register type	Quantity	Operation	Data Range/Remarks	Related function codes
Module MAC address	0x0898	4-2201	Holding register	3	R	Device MAC parameter	R：0x03
Local IP address	0x089B	4-2204	Holding register	2	RW	Default：192.168.3.7	R：0x03 W：0x06、0x10
Local port	0x089D	4-2206	Holding register	1	RW	1～65535，default：502	R：0x03 W：0x06、0x10
Subnet mask	0x089E	4-2207	Holding register	2	RW	Default：255.255.255.0	R：0x03 W：0x06、0x10
Gateway address	0x08A0	4-2209	Holding register	2	RW	Default：192.168.3.1	R：0x03 W：0x06、0x10
DHCP mode configuration	0x08A2	4-2211	Holding register	1	RW	0x0000 static IP（default） 0x0001 automatically get IP	R：0x03 W：0x06、0x10
Target IP/Domain Name	0x08A3	4-2212	Holding register	64	RW	Store in strings IP/Domain Name Default IP：192.168.3.3	R：0x03 W：0x06、0x10
Server port	0x08E3	4-2276	Holding register	1	RW	0-65535，Default 502	R：0x03 W：0x06、0x10
DNS server IP address	0x08E4	4-2277	Holding register	2	RW	Default 8.8.8.8	R：0x03 W：0x06、0x10
Module operating mode	0x08E6	4-2279	Holding register	1	RW	0x0000 server mode 0x0001 client mode	R：0x03 W：0x06、0x10
Active upload	0x08E7	4-2280	Holding register	1	RW	0x0000 prohibited， Other： Send in 1～65535s	R：0x03 W：0x06、0x10
MOSBUS TCP/RTU conversion	0x08E8	4-2281	Holding register	1	RW	0,turn off，1turn on	R：0x03 W：0x06、0x10
MODBUS addrss filtering	0x08E9	4-2282	Holding register	1	RW	0: Transparent transmission, 1-255: When non local data is present, check the slave address of the instruction instruction. When it is set to a value, it can be passed through the	R：0x03 W：0x06、0x10

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4.9.6 Modbus command operation

1. Read coil (DO) status

Use the read coil status (01) function code to read the output coil status, for example:

01	01	00 00	00 04	3D C9
Modbus address	Function code	Register first address	Output coil quantity	CRC check code

After the above command is sent to the device through the 485 bus, the device will return the following values:

01	01	01	01	90 48
Modbus address	Function code	Number of bytes of data	Status data returned	CRC check code

The above returned status data 01 indicates that the output DO1 is turned on.

2. Control coil (DO) status

Support operation of single coil (05), operation of multiple coils (0F) function code operation. Use the 05 command to write a single command, for example:

01	05	00 00	FF 00	8C 3A
Modbus address	Function code	Register first address	On：FF 00 Off：00 00	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	05	00 00	FF 00	8C 3A
Modbus address	Function code	Register first address	Operation method	CRC check code

DO1 coil conduction

Use the 0F function code as the command to write multiple coils, for example:

01	0F	00 00	00 04	01	0F	7E 92
Modbus address	Function code	Starting address	Coil number	Number of bytes of data	Data of control coil	CRC check code

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After the above command is sent to the device through the 485 bus, the device will return the following values

01	0F	00 00	OO O4	54 08
Modbus address	Function code	Register address	Coil number	CRC check code

All coils are conducted.

3. Read Holding register

Use the 03 function code to read one or more register values, for example:

01	03	05 78	00 01	04 DF
Modbus address	Function code	Register first address	Quantity of register read	CRC check code

After the above command is sent to the device through the 485 bus, the device will return the following values:

01	03	02	00 00	B8 44
Modbus address	Function code	Number of bytes of data	Data returned	CRC check code

The above 00 00 indicates that DO1 is in level output mode.

4. Operate Holding register

Support operation of single register (06), operation of multiple registers (10) function code operation.

Use the 06 function code to write a single Holding register, for example: set the working mode of DO1 to pulse mode

01	06	05 78	00 01	C8 DF
Modbus address	Function code	Register address	Write value	CRC check code

After the above command is sent to the device through the 485 bus, the device will return the following values:

01	06	05 78	00 01	C8 DF
Modbus address	Function code	Register address	Write value	CRC check code

If the modification is successful, the 0x0578 register data is 0x0001, and the pulse output mode is turned on.

Use the 10 function code to write multiple holding register commands, for example: set the working mode of DO1 and DO2 at the same time.

01	10	05 78	00 02	04	00 01 00 01	5A 7D
Modbus address	Function code	Register first address	Register number	Quantity of bytes of written data	Written data	CRC check code

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After the above command is sent to the device through the 485 bus, the device will return the following values:

01	10	05 78	00 02	C1 1D
Modbus address	Function code	Register address	Register quantity	CRC check code

If the modification is successful, the values of the two consecutive registers with 0x0578 as the starting address are 0x0001 and 0x0001 respectively to identify DO1 and DO2 to enable pulse output.

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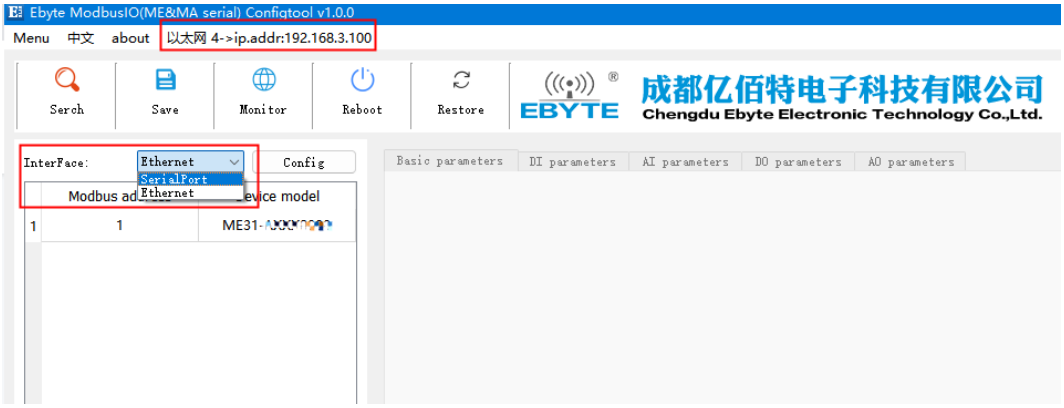
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5 Host computer

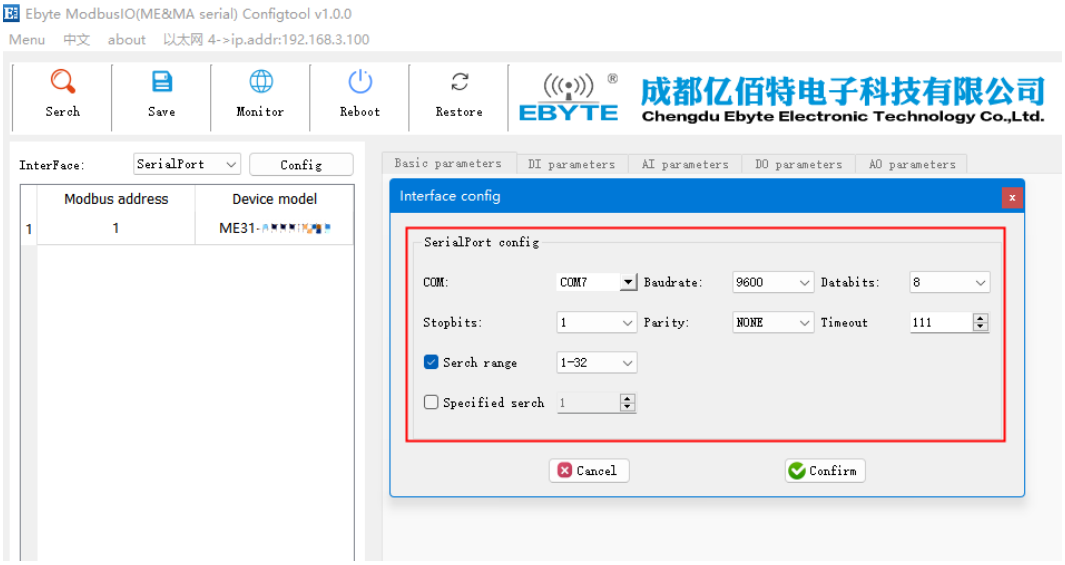
5.1 Acquisition and control

Step 1: Connect the computer to the device

(1) The device can be configured by selecting interfaces (serial/network); If you choose a network port, you need to first select the network card before searching for devices.



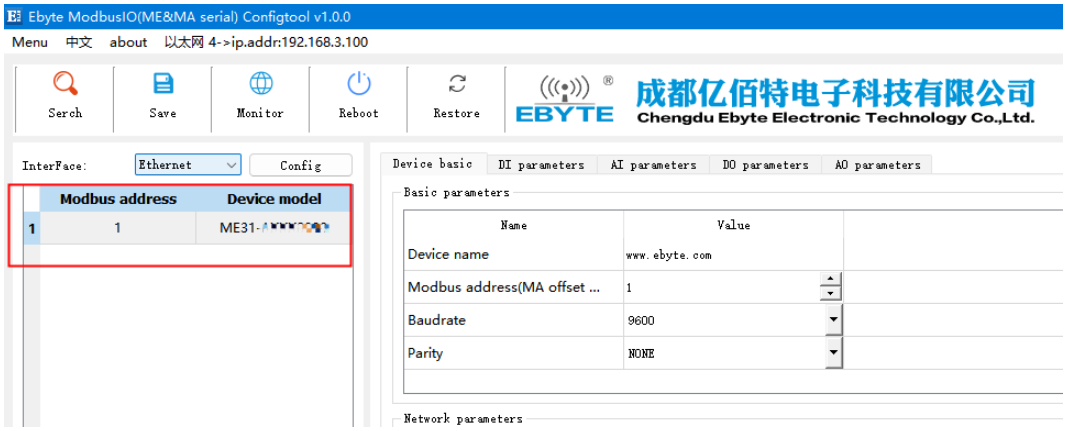
(2) If you select a serial port, you need to select the corresponding serial port number and the same Baud, data bit, stop bit, check bit and address segment search range as the device, and then search.



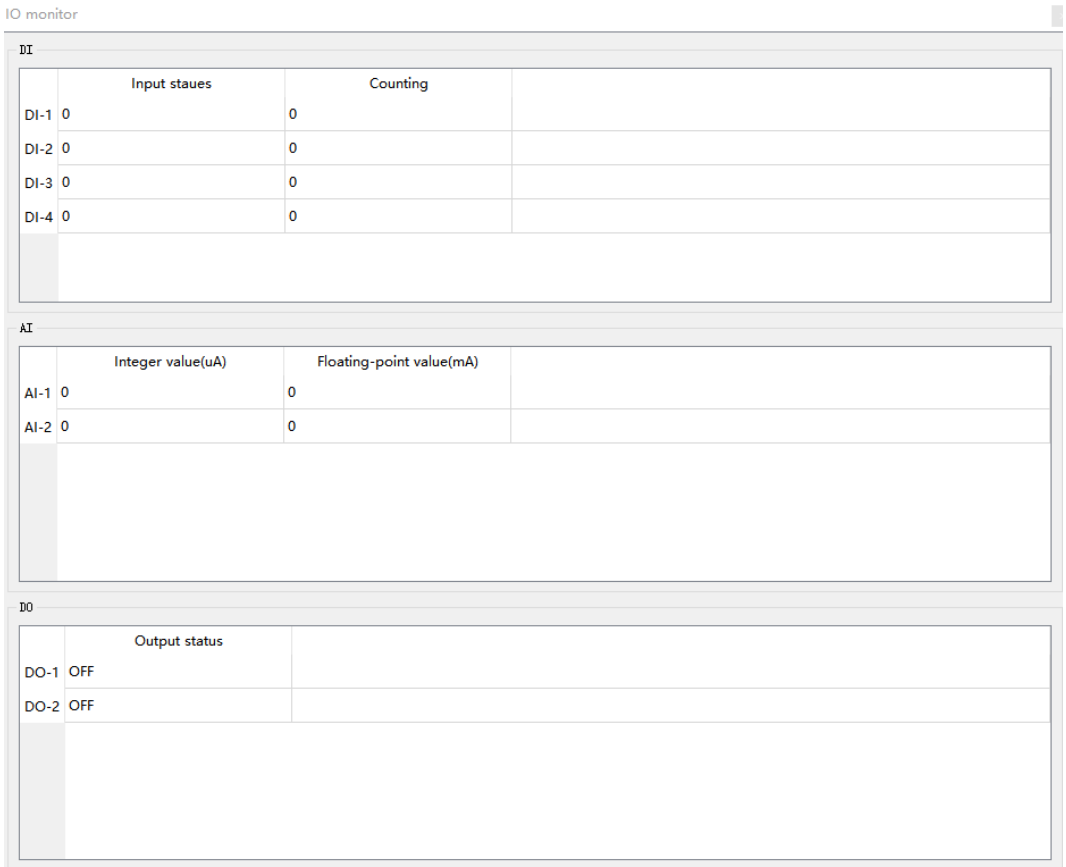
Step 2: Select the right device

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Step 3: Click on the device online to enter IO monitoring. The following is the IO monitoring screen display



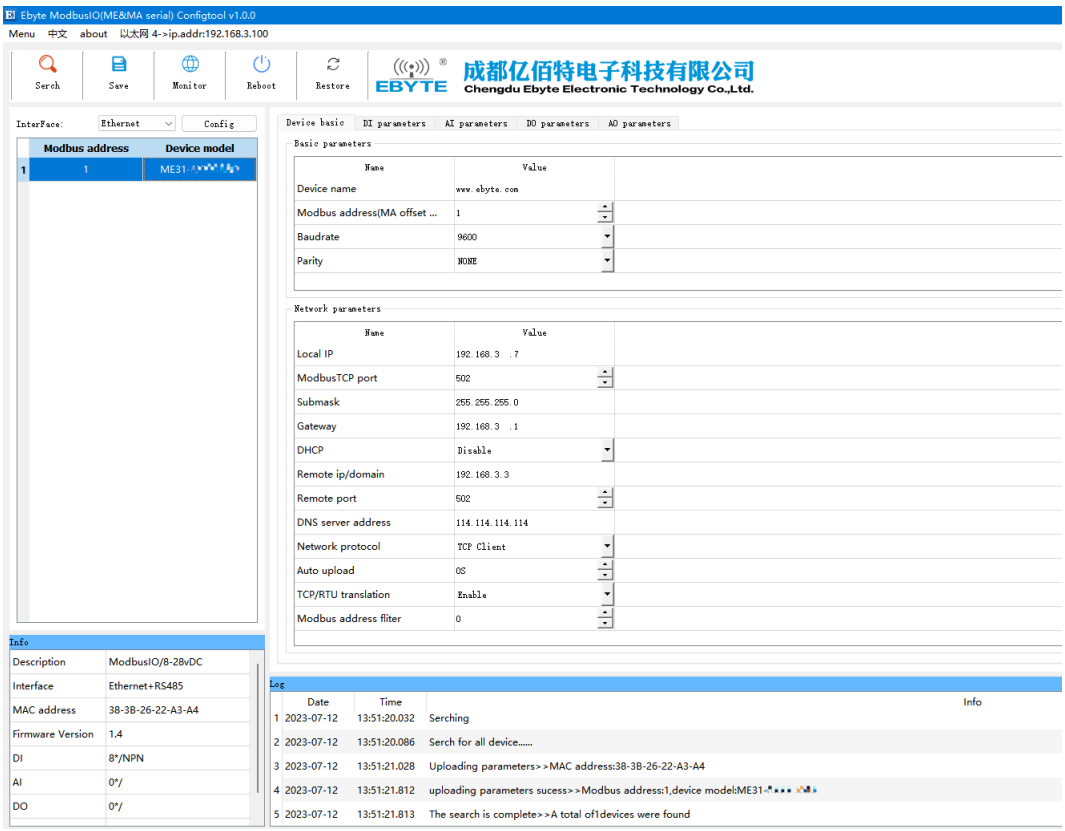
5.2 Parameter Configuration Interface

Step 1: Connect the device according to "Collection and Control"

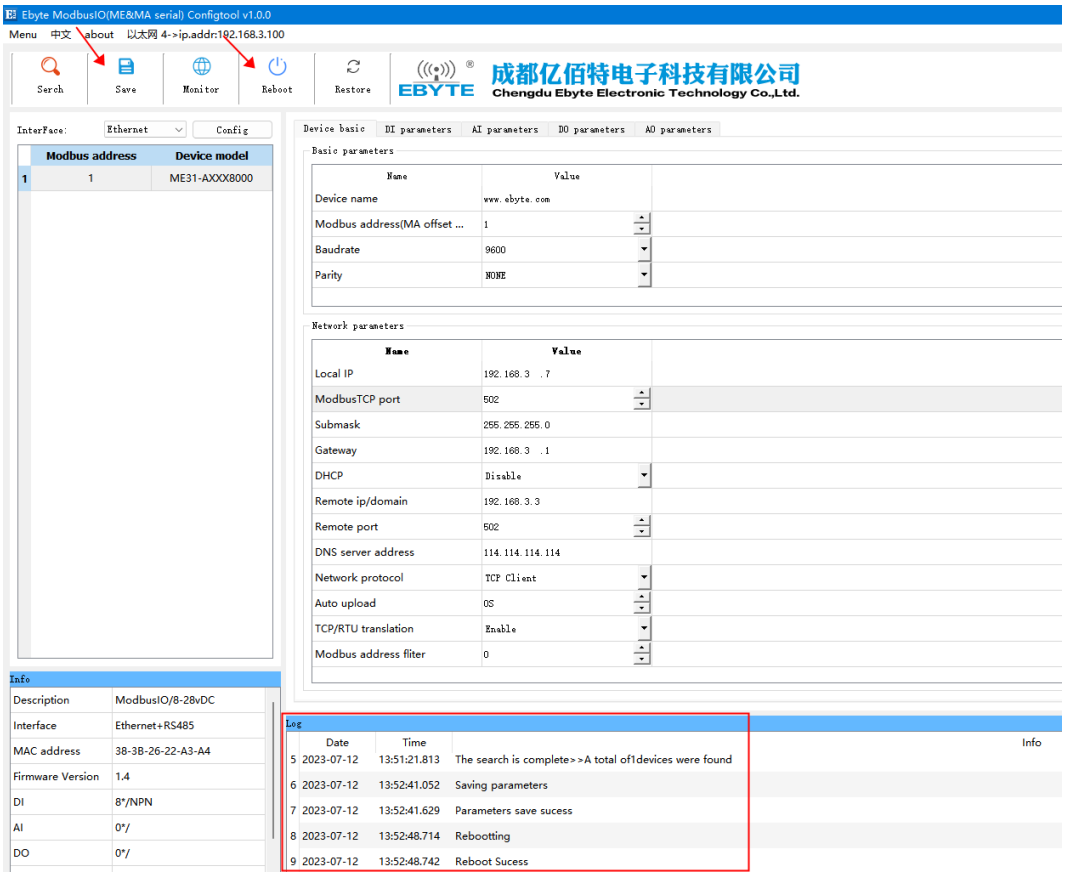
Step 2: You can configure device parameters, network parameters, DI parameters, AI parameters, DO parameters, and AO parameters (for example, if the device does not have AO function, AO parameters cannot be configured)

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Step 3: After configuring the parameters, click to download them. In the log output, you will see a prompt stating that the parameters have been successfully saved. Click to restart the device. After the device restarts, the modified parameters will take effect.



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