EBYTE

成都亿佰特电子科技有限公司

Chengdu Ebyte Electronic Technology Co.,Ltd.

Wireless Modem

USER MANUAL



ME31-AAAX2240

Network I/O Networking Module

This manual may be updated with product improvements, please refer to the latest version of the manual! Chengdu Yibaite Electronic Technology Co., Ltd. reserves the final interpretation and modification rights for all contents in this instruction!

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I. Overview

1.1 Product Introduction



ME31-AAAX2240 is equipped with 4-way A-type relay output, 2-way analog (0-20mA/4-20mA) input, 2-way dry contact input detection, and supports Modbus TCP protocol or Modbus RTU protocol for acquisition and control. At the same time, the device is also a network I/O networking module that can be used as a simple Modbus gateway (automatically send commands with non-local Modbus addresses through the serial port/network port).

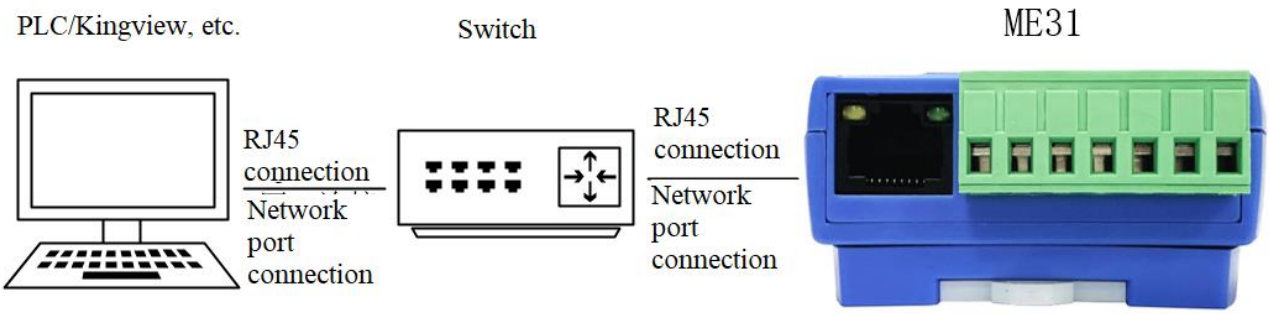
1.2 Functional Features

- Support standard Modbus RTU protocol and Modbus TCP protocol;
- Support various configuration software/PLC/touch screen;
- RS485 acquisition control I/O;
- RJ45 acquisition control I/O, support 4-way host access;
- Support OLED display to display status information, and configure device parameters through buttons;
- 2-way analog input (0-20mA/4-20mA);
- 2-way switch input DI (dry node);
- 4-way switch output DO (Type A relay);
- Switch output (DO) supports level mode, pulse mode, follow mode, reverse follow mode, trigger flip mode;
- Support custom Modbus address setting;
- Support 8 common baud rate configurations;
- Support DHCP and static IP;
- Support DNS function, domain name resolution;
- Support Modbus gateway function;
- Support input and output linkage；

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1.3 Product Application Topology Diagram



Network interface application topology diagram



Serial port application topology diagram

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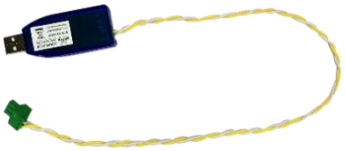
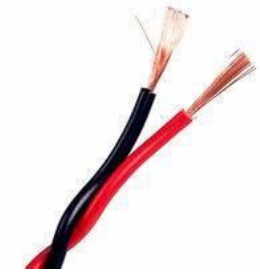
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II.Quick use

【Note】This test needs to be carried out with the default factory parameters.

2.1 Device preparation

The following table lists the items required for this test:

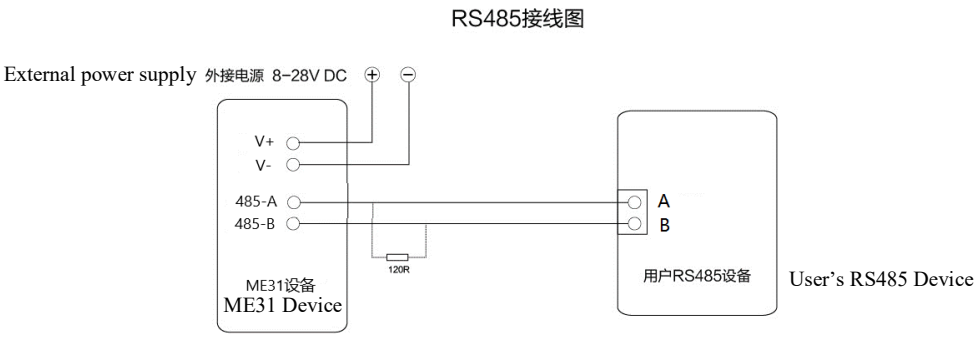
		
ME31-AAAX2240	12V switching power supply	USB to RS485 Cable
		
A computer	A network cable	Several cables

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2.2 Device connection

2.2.1 RS485 connection

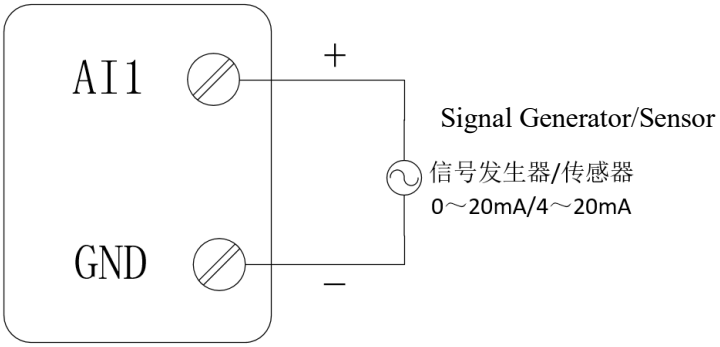


Note: When the 485 bus high-frequency signal is transmitted, the signal wavelength is shorter than the transmission line, and the signal will form a reflected wave at the end of the transmission line, which will interfere with the original signal. Therefore, it is necessary to add a terminal resistor at the end of the transmission line so that the signal does not reflect after reaching the end of the transmission line. The terminal resistance should be the same as the impedance of the communication cable, the typical value is 120 ohms. Its function is to match the bus impedance and improve the anti-interference and reliability of data communication.

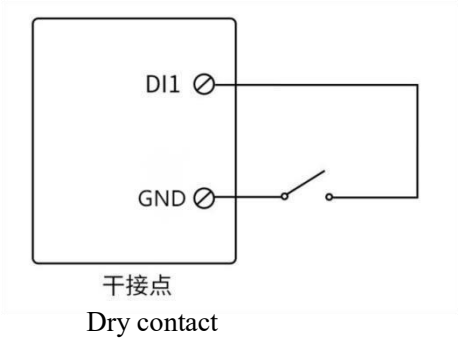
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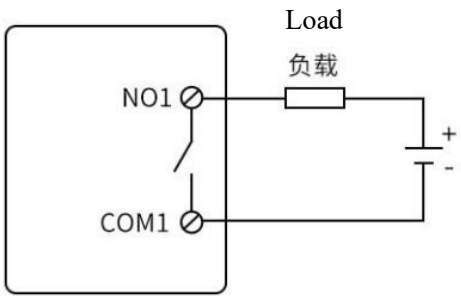
2.2.2 AI analog input connection



2.2.3. DI switch input connection



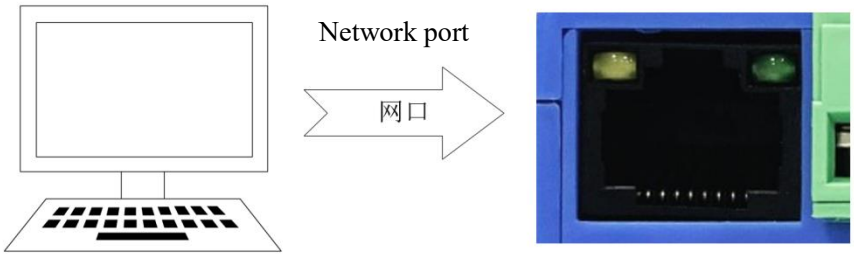
2.2.4. Relay output connection



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2.2.5 Simple use



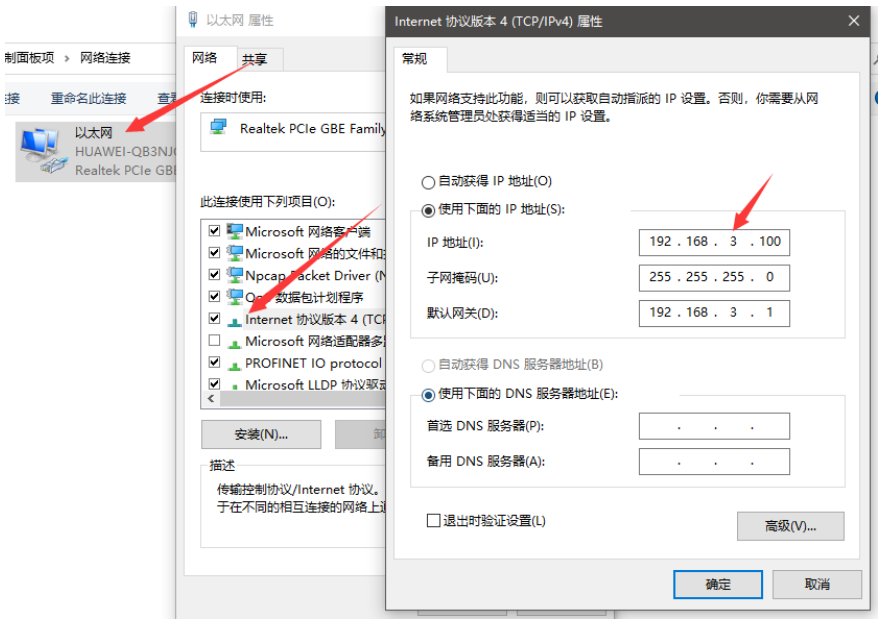
Wiring: The computer is connected to the RS485 interface of ME31-AAAX2240 through USB to RS485, A is connected to A, and B is connected to B.

Networking: Insert the network cable into the RJ45 port and connect to the PC.

Power supply: Use DC-12V switching power supply (DC 8~28V) to power ME31-AAAX2240.

2.3 Parameter Configuration

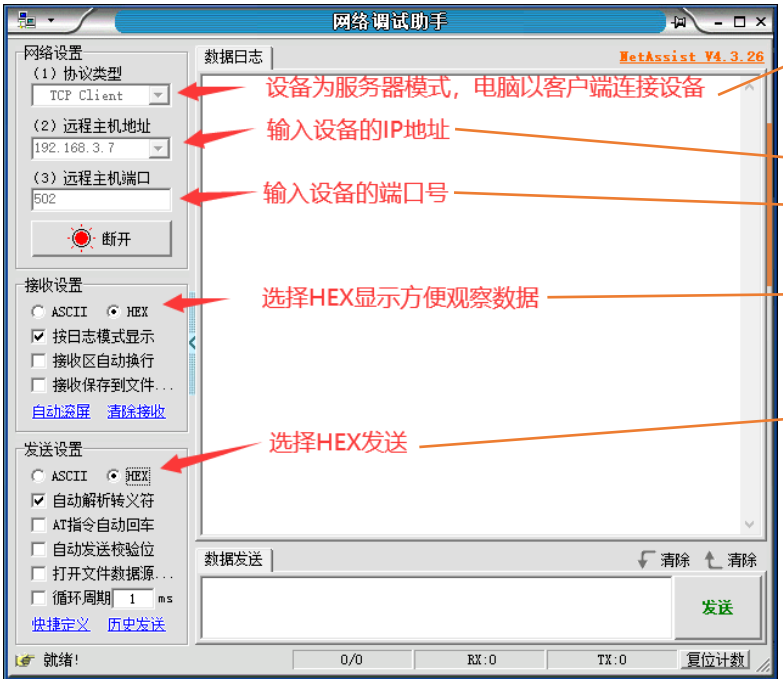
Step 1: Modify the IP address of the computer to be consistent with the device. Here I am modifying it to 192.168.3.100 to ensure that it is on the same network segment as the device and that the IP is different. If you cannot connect to the device after the above steps, please turn off the firewall and try again;



Step 2: Open the network assistant, select the TCP client, enter the remote host IP192.168.3.7 (default parameter), enter the port number 502 (default parameter), and select HEX to send.

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The device is in server mode, and the computer connects to the device as a client.

Enter the IP address of the device.

Enter the port number of the device.

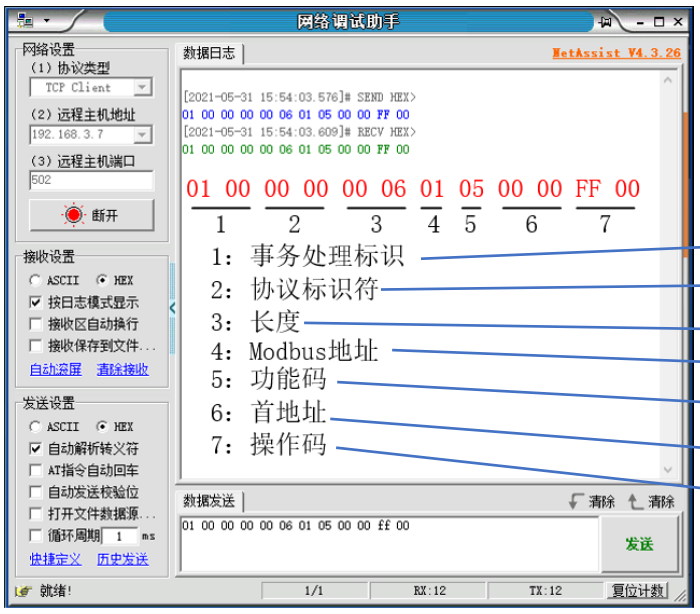
Select HEX display to facilitate observation of data.

Select HEX to send

2.4 Control Testing

2.4.1 Modbus TCP control

Use the network assistant to control the first DO output of ME31-AAAX2240.



1: Transaction ID

2: Protocol identifier

3: Length

4: Modbus address

5: Function code

6: First address

7: Opcode

Other functions can be tested through the commands in the table below.

Function (function code)	Command

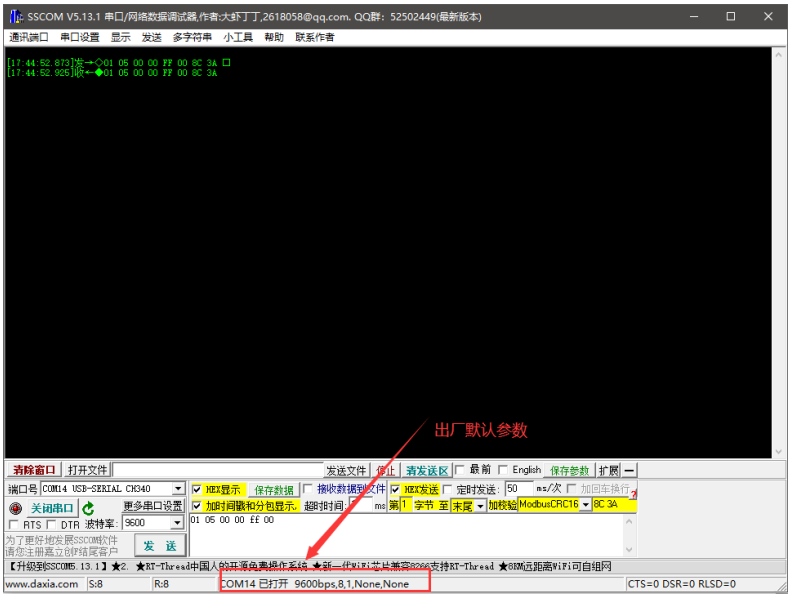
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Pull in the first coil (0x05)	01 00 00 00 00 06 01 05 00 00 FF 00
Full open command (0x0F)	02 00 00 00 00 08 01 0F 00 00 00 04 01 0F
Full close command (0x0F)	02 00 00 00 00 08 01 0F 00 00 00 04 01 00
Read all DI status (0x02)	01 00 00 00 00 06 01 02 00 00 00 02
Read all DO status (0x01)	01 00 00 00 00 06 01 01 00 00 00 04

2.4.2 Modbus RTU control

Use the serial port assistant to control the first DO output of ME31-AAAX2240.



Other functions can be tested through the commands in the table below.

Function (function code)	Command
Pull in the first coil (0x05)	01 05 00 00 FF 00 8C 3A
Full open command (0x0F)	01 0F 00 00 00 04 01 0F 7E 92
Full close command (0x0F)	01 0F 00 00 00 04 01 00 3E 96
Read all DI status (0x02)	01 02 00 00 00 02 F9 CB
Read all DO status (0x01)	01 01 00 00 00 04 3D C9

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III. Technical Specification

3.1 Specifications

Category	Name	Parameters
Power supply	Operating Voltage	DC8～28V
	Power indicator	Blue LED indication
Serial port	Communication Interface	RJ45, RS485
	Baud rate	9600bps (customizable)
	Protocol	Standard Modbus TCP, Modbus RTU protocol
MODBUS	Device address	Can be modified by Modbus command and host computer
DI input	Number of DI channels	2 way
	Input type	Default dry contact
	Acquisition frequency	1 kHz
	Input instructions	OLED screen display, red LED indication
AI input	AI channels	2 way
	Acquisition Features	Single-ended input
	Input type	0-20mA, 4-20mA
	AI resolution	3‰
	Acquisition frequency	10Hz
	Input instructions	OLED screen display
DO output	Number of DO channels	4 way
	DO output type	Form A relay
	DO output mode	Level output, pulse output
	Relay contact capacity	30V/5A、250V/5A
	Output indication	OLED screen display, red LED indication
Other	Product Size	121mm * 72mm * 34mm (L*W*H)
	Product weight	145±5g
	Working temperature and humidity	-40 ～ +85℃, 5% ～ 95%RH (no condensation)
	Storage temperature and	-40 ～ +105℃, 5% ～ 95%RH (no condensation)

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	humidity	
	Installation method	Din-rail installation

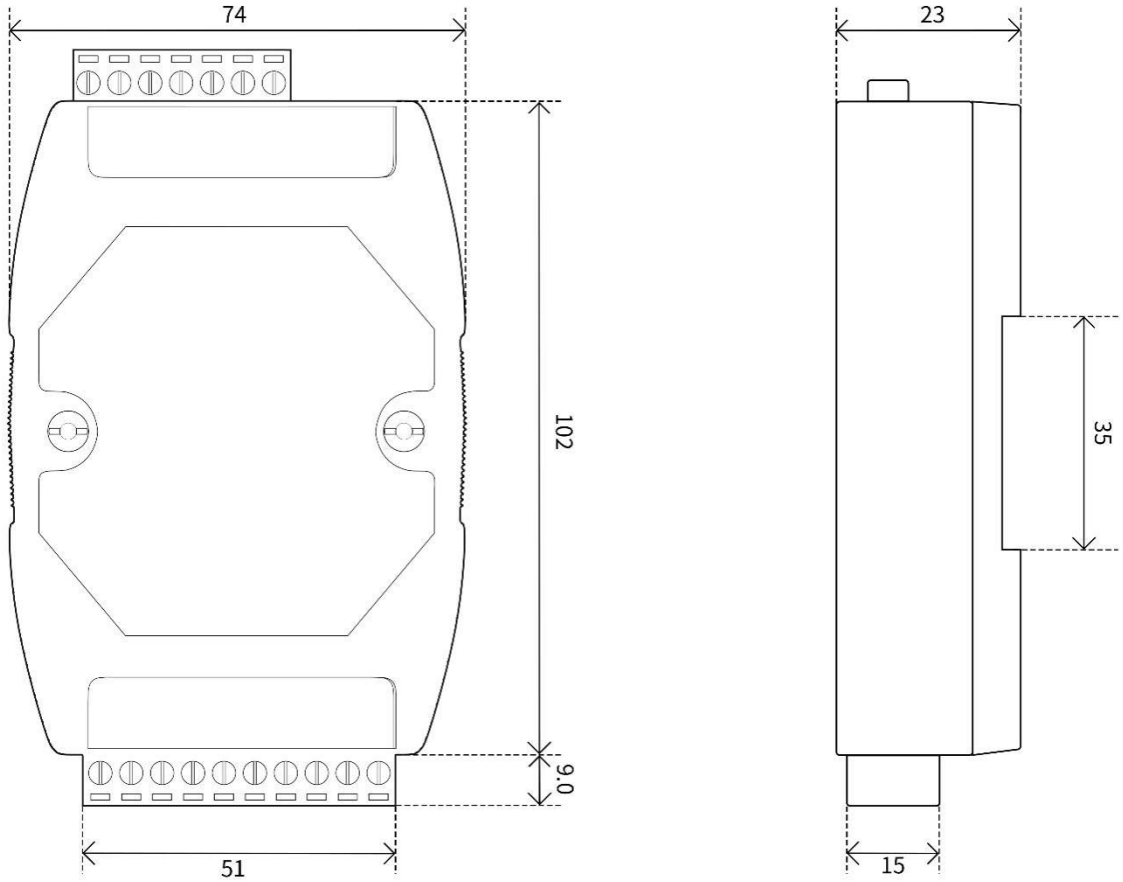
3.2 Device Default Parameters

Category	Name	Parameters
Ethernet parameters	Operating mode	TCP server (up to 4-way client access)
	Local IP	192.168.3.7
	Local port	502
	Subnet mask	255.255.255.0
	Gateway address	192.168.3.1
	DHCP	Close
	Native MAC	Determined by the chip (fixed)
	Target IP	192.168.3.3
	Target port	502
	DNS server	114.114.114.114
	Active upload	Close
Serial parameters	Baud rate	9600bps (8 types)
	Check method	None (default), Odd, Even
	Data bit	8
	Stop bit	1
MODBUS parameter	Modbus master-slave	Slave
	Address	1

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3.3 Mechanical Dimensional Drawing



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3.4 Port and indicator light description



No.	Label	Illustrate
1	TX（LED）	Serial port send data indicator light
2	RX（LED）	Serial port receiving data indicator light
3	LINK（LED）	Network connection light
4	NET（LED）	Network data sending and receiving indicator light
5	PWR（LED）	Power input indicator
6	DO1（LED）	The first relay output indicator
7	DO2（LED）	The second relay output indicator
8	DO3（LED）	The third relay output indicator
9	DO4（LED）	The fourth relay output indicator
10	GND	Negative pole of power input terminal, DC 8V~28V, 5.08mm Phoenix terminal.
11	VCC	Positive pole of power input terminal, DC 8V~28V, 5.08mm Phoenix terminal.
12	NO1	Relay 1 normally open pin, used with relay 1 common terminal, 5.08mm Phoenix terminal.
13	COM1	Common terminal of relay 1, used in conjunction with the normally open pin of relay 1, 5.08mm Phoenix terminal.

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14	NO2	Relay 2 normally open pin, used with relay 2 common terminal, 5.08mm Phoenix terminal.
15	COM2	Common terminal of relay 2, used in conjunction with the normally open pin of relay 2, 5.08mm Phoenix terminal.
16	NO3	Relay 3 normally open pin, used with relay 3 common terminal, 5.08mm Phoenix terminal.
17	COM3	Common terminal of relay 3, used in conjunction with the normally open pin of relay 3, 5.08mm Phoenix terminal.
18	NO4	Relay 4 normally open pin, used with relay 4 common terminal, 5.08mm Phoenix terminal.
19	COM4	Relay 4 common terminal, used with relay 4 normally open pin, 5.08mm Phoenix terminal.
20	Ethernet	Ethernet interface, standard RJ45 interface.
21	AI2	Analog input channel 2, supports 0 to 20mA current input, 5.08mm Phoenix terminal.
22	AI1	Analog input channel 1, supports 0 to 20mA current input, 5.08mm Phoenix terminal.
23	DI2	Digital input channel 2, supports dry contact access, 5.08mm Phoenix terminal.
24	DI1	Digital input channel 1, supports dry contact access, 5.08mm Phoenix terminal.
25	GND	Signal ground, 5.08mm Phoenix terminal.
26	485-A	The A of the serial port is connected to the A interface of the external device, and the 5.08mm Phoenix terminal.
27	485-B	The B of the serial port is connected to the B interface of the external device, and the 5.08mm Phoenix terminal.

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IV. Product Function Introduction

4.1 DI Input

4.1.1. Switch Input DI Collection

The switch input DI measures level signals or edge pulse signals (rising edge, falling edge). Support dry contact collection, support DI counting function, the maximum counting value is 65535 (the count exceeding 65535 is automatically cleared).

The switch input DI supports three trigger modes: rising edge, falling edge, and level (default rising edge trigger).

The clearing method supports automatic clearing and manual clearing (default automatic clearing).

4.1.2. Input filtering

When the switch inputs DI to collect signals, it needs to maintain multiple sampling periods before confirming. Filter parameters can be set in the range of 1 to 16 (default 6 sampling periods, 6*1kHz).

It can be configured with the host computer through instructions.

4.2 AI Input

4.2.1. Analog range

The analog input AI measures the current signal, the acquisition range is 0-20mA or 4-20mA, the precision is 3‰, and the resolution is 12 bits. The device adopts single-ended input, the sampling frequency is 10Hz, and the input impedance is 100Ω.

Set the sampling range of all AI channels, valid values are 1 and 0 (default 0).

Configured as 0: means 0~20mA

Configured as 1: means 4~20mA

[Note] AI configuration instructions

（1） The AI sampling range of each channel can be set. When the AI channel sampling range is configured as 4~20mA sampling, if the current signal is lower than 3.5mA, it will be displayed as 0, and if it is higher than 3.5 mA and lower than 4mA, it will be displayed as 4. There is no conversion limit for signals greater than 20mA, but it cannot exceed 25mA (there is a risk of equipment damage if it exceeds 25mA).

（2） The starting address of the AI channel sampling range parameter is 0x04B2, the register type is a holding register, and the function codes are 0x06 and 0x10. When writing AI channel sampling range parameters, if the written parameter value is not within the range of 0 to 1, it will automatically take the closest value and write it in. If the sampling range parameter is 2, the device will take 1 as the sampling range parameter. And Modbus does not return error commands.

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4.2.2. Trigger mode

（1）Not trigger: mode off.

（2）Rising Trigger: When the AI input value becomes greater than the set AI trigger high value, a rising edge trigger occurs, changing the state of the DO. For the rising edge trigger to change the DO state again, the AI input value must be lower than the set AI trigger low value for the rising edge trigger to take effect again (the DO working mode needs to be set to trigger flip mode).

（3）Falling Trigger: When the AI input value becomes lower than the set AI trigger high value, a falling edge trigger occurs, changing the state of the DO. For the falling edge trigger to change the DO state again, the AI input value must be higher than the set AI trigger high value for the falling edge trigger to take effect again (the DO working mode needs to be set to trigger flip mode).

（4）Dual-Edge Trigger: When the AI input value becomes greater than the set AI trigger high value, the AI trigger becomes high (i.e., the DO output state changes once), generating a rising edge trigger. After triggering, as long as the AI value does not drop below the set AI trigger low value, the current DO output value remains unchanged. When the AI input value becomes lower than the set AI trigger low value, the AI trigger becomes low (i.e., the DO output state changes once), generating a falling edge trigger. After triggering, as long as the AI value does not exceed the set AI trigger high value, the current DO output value remains unchanged (the DO working mode needs to be set to trigger flip mode).

4.2.3. Engineering quantity shaping value and engineering quantity floating point value of analog input

There are two ways to read the current signal collected by the device:

（1） Read the AI engineering quantity shaping value, and directly convert to get the input current. The starting address of the AI engineering quantity shaping value register is 0x0064, the register type is an input register, and the read function code is 0x04. The value returned by this method represents one channel per register, and the value read is 0 to 25000. The method of calculating the current size is 0~25000 corresponding to 0~25mA. That is:

Current = engineering value / 1000 (mA)

（2） Read the floating-point value of the AI engineering quantity, and use the IEE754 conversion tool to convert the hexadecimal data into a floating-point number to obtain the input current. The starting address of the AI engineering quantity shaping value register is 0x00C8, the register type is an input register, and the read function code is 0x04. This method returns two registers representing 1 channel.

4.2.4. AI filter parameters

You can set the filter parameters of the AI channel, the effective value is 1-16, and the default value is 6.

Description of filter parameters:

（1）All AI channels share a filter parameter. The higher the parameter value, the more stable the output value and the slower the response.

（2）The AI channel filter parameter address is 0x04B0, and the register type is a holding register. Function code 0x06, 0x10.

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（3）When writing AI filter parameters, if the written parameter value is not within the range of 1 to 16, it will automatically take the closest value and write it in. If the filter parameter is written as 0, the device will take 1 as the filter parameter, and Modbus does not return error commands.

4.3 DO output

Relay output mode: output different mode output according to the mode set by the user, and the level output is turned on by default.

4.3.1. Input count

Support counting DI input, users can configure rising edge acquisition, falling edge acquisition, and level acquisition according to their own needs. You can also change the clearing method according to your needs.

Trigger method:

Rising edge: When the rising edge is collected (it is not counted when it is turned on, it is counted when it is turned off), it will be counted once.

Falling edge: When the falling edge is collected (counting when it is turned on, and not counting when it is released), count once.

Level: Two edges are collected and counted once respectively.

Clearing method:

Automatic: The device will automatically clear each time the DI count value register (0x09DF~0x09E6) is read.

Manual: In manual mode, it is necessary to write 1 to the clear signal register (0x0AA7~0x0AAE), and each holding register controls one clear signal.

4.3.2. Level output

Output according to the level set by the user, the switch characteristic of the level mode is similar to the function of a self-locking switch.

4.3.3. Pulse output

After the switch output DO is turned on, the switch output DO is automatically turned off after maintaining the set pulse width time (in ms). The pulse width setting range is 50~65535ms (50ms by default).

4.3.4. Follow mode

According to the follow source configured by the user (when the device has AI acquisition or DI detection function, both DI or AI can be used as the follow source, otherwise this function is useless) to change the relay state, and multiple outputs can follow the same follow source output. To put it simply, DI detects the input, and automatically outputs a relay that uses it as a follow source (for example: DI is 1, DO is closed). When the follow mode is turned on, the follow source should be configured at the same time, otherwise it will follow the first input by default.

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4.3.5. Reverse follow mode

According to the follow source configured by the user (when the device has AI acquisition or DI detection function, both DI or AI can be used as the follow source, otherwise this function is useless) to change the relay state, and multiple outputs can follow the same follow source output. To put it simply, DI detects the input, and automatically outputs the relay that follows it as the source (for example: DI is 1, DO is disconnected). When the follow mode is turned on, the follow source should be configured at the same time, otherwise it will follow the first input by default.

4.3.6. Trigger toggle mode

According to the follow source configured by the user (when the device has AI acquisition or DI detection function, both DI or AI can be used as the follow source, otherwise this function is useless) to change the relay state, and multiple outputs can follow the same follow source output. Simply put, when DI generates a trigger signal (rising edge or falling edge), DO will have a state change. When the trigger flip mode is turned on, the following source should be configured at the same time, otherwise it will follow the first input by default.

4.3.7. Power-on state

According to the state set by the user. After the device is powered on, the output relay is turned on according to the state set by the user, and it is turned off by default.

4.4 Modbus Gateway

The device can transparently transmit non-native Modbus commands from the network/serial port to the serial port/network, and the local Modbus commands are directly executed.

4.4.1. Modbus TCP/RTU protocol conversion

After it is turned on, the Modbus TCP data on the network side will be converted to Modbus RTU data.

4.4.2. Modbus Address Filtering

This function can be used when some host software or configuration screen is used as the host to access the serial port of the device, and the gateway function of the device is used, the slave is at the network end, and the Modbus TCP to RTU function is turned on. Multiple slaves on the bus may cause data confusion. At this time, enabling address filtering can ensure that only the specified address can pass through the device; when the parameter is 0, the data will be transparently transmitted; when the parameter is 1-255, only the set slave machine address data.

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4.4.3. Modbus TCP Protocol Data Frame Description

TCP frame format：

Transaction ID	Protocol ID	Length	Device address	Function code	Data segment
2 Bit	2 Bit	N+2 Bit	1 Bit	1 Bit	N Bit

- Transaction ID: It can be understood as the serial number of the message. Generally, 1 is added after each communication to distinguish different communication data messages.
- Protocol identifier: 00 00 means Modbus TCP protocol.
- Length: Indicates the length of the next data in bytes.

Example: get DI status

01 00	00 00	00 06	01	02	00 00 00 04
Transaction ID	Protocol ID	Length	Device address	Function code	Data segment

4.4.4. Modbus RTU protocol data frame description

RTU frame format：

Device address	Function code	Data segment	Check codeCRC
1 Bit	1 Bit	N Bit	2 Bit

Example: get DI status command

01	02	00 00 00 04	79 C9
Device Modbus address	Function code	Data segment	CRC check code

4.5 IO linkage function

The linkage function is divided into AI-DO linkage and DI-DO linkage. Generally speaking, the linkage function needs to be divided into two parts. The first part is the trigger source: that is, AI/DI input, and the second part is the trigger: that is, DO/AO output.

1. When DI is used as the trigger source, DI input status and DI changes can be used as signals, according to the corresponding configuration of DO:

a. In follow/reverse follow mode, the current state of DI will be used as a signal, and the states of DO and DI are the same/opposite;

b. Trigger inversion mode, DI state change is used as a signal, if the trigger signal is set to DI rising edge change, the current state of DO will change once.

2. When AI is used as the trigger source, the AI signal is processed into a signal similar to DI through a process similar to Schmitt trigger (refer to Chapter 4.2.2), and then this signal is linked with DO. The linkage process can refer to DI/ DO linkage.

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4.6 Active upload

The device supports the function of uploading analog input values at regular intervals. Setting the value of the corresponding register can control the interval time and whether to upload.

Devices with digital input will actively upload once after successfully connecting to the server, and then the digital input will be uploaded following the status change. Devices with analog input will report the status of analog input according to the configured active upload time period (the configuration period is 1-65535).

When it is set to 0, the upload is disabled; if it is set to other positive integer value N, the upload will be performed at intervals of N seconds.

[Note] The device can only be valid if it is configured in client mode, and the register value is non-zero to enable active upload.

4.7 Custom Module Information

4.7.1. Modbus Address

The device address is 1 by default, and the address can be modified, and the address range is 1-247.

4.7.2. Module Name

Users can configure the device name according to their own needs to distinguish, support English, digital format, up to 20 bytes.

4.7.3. Network parameters

Unless otherwise specified: the following network-related parameters default to IPV4-related parameters.

(1) MAC of the device: the user can obtain it by reading the specified register, and this parameter cannot be written.

(2) IP address: device IP address, readable and writable.

(3) Modbus TCP port: the port number of the device, readable and writable.

(4) Subnet mask: address mask, readable and writable.

(5) Gateway address: gateway.

(6) DHCP: Set the way the device obtains IP: static (0), dynamic (1).

(7) Target IP: When the device works in client mode, the target IP or domain name of the device connection.

(8) Destination port: When the device is working in client mode, the destination port of the device connection.

(9) DNS server: The device is in the client mode and resolves the domain name of the server.

(10) Module working mode: switch the working mode of the module. Server: The device is equivalent to a server, waiting for the user's client to connect. The maximum number of connections is 4. Client: The device actively connects to the target IP and port set by the user.

(11) Active upload: When this parameter is not 0, and the device is in the client mode, the discrete input status

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of the device will be uploaded to the server when it is connected for the first time or the input changes, and the analog input will be uploaded according to the configured time period.

4.7.4. Serial Port Parameters

Parameters for setting serial communication:
Default parameters:
Baud rate: 9600 (03);
Data bit: 8bit;
Stop bit: 1bit;
Check digit: NONE(00);

(1) Baud rate：

Baud rate code value table	
0x0000	1200
0x0001	2400
0x0002	4800
0x0003 （default）	9600
0x0004	19200
0x0005	38400
0x0006	57600
0x0007	115200

(2) Check Digit：

Check Digit	
0x0000(默认)	NONE
0x0001	ODD
0x0002	EVEN

4.8 OLED display and parameter configuration

The display interface includes an information display page (AI input value and DI input status, DO status display page) and a parameter setting page (some parameters).

4.8.1. Information Display Interface

Including AI input value, DI input status, and DO status display page, short press the up and down buttons to switch the interface.

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4.8.2. Equipment parameter display interface

Press the left or right button to enter the password input interface, complete the correct password input, and display the device parameter information interface (password interface: default password: 0000. Short press the middle to verify the password; The left and right buttons can switch the password bit; Up and down keys can switch the value of the current bit. The password has a total of 4 digits, and each input is a number ranging from 0-9):

The parameter setting interface from top to bottom is:

1. Modbus address;
2. Baud rate;
3. Data bits;
4. Check Digit;
5. Stop bit;
6. Local port;
7. Local IP address;
8. Network mode;
9. Gateway;
10. Subnet mask;
11. DNS;
12. MAC address;
13. DHCP;
14. Target IP;
15. Destination port;
16. Modbus TCP/RTU protocol conversion;
17. Active upload;
18. Modbus address filtering;；

4.8.3. Equipment Parameter Configuration Interface

Press and hold the confirmation button to enter the password input interface, complete the correct password input, and enter the configuration interface (password interface: default password: 0000; short press the middle to verify the password, the left and right buttons switch the password bit, and the up and down buttons switch the value of the current bit , the password has a total of 4 digits, and each input range is a number from 0-9).

Select the setting item, enter the parameter configuration page and short press the up and down keys to switch the setting item;

Select the setting item, short press to confirm or right click, the setting item gets the cursor to represent the selection and enter the setting item;

Adjust the parameter value: After selecting the setting item, the up and down keys can change the value or optional value; the left and right keys move the cursor in the parameter item;

Confirm the parameter value: After adjusting the parameter value, press the enter key to exit the current setting item.

Save parameter settings and restart: After setting the parameters, move the cursor to save and restart, then short press the confirmation key to enter the confirmation save and restart state. Short press the confirmation key (press other keys to exit the confirmation state) to save the parameters and restart the device.

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Exit without saving parameters: move the cursor to exit, then short press the confirmation key to enter the confirmation exit state, short press the confirmation key (press other keys to exit the confirmation state), and then exit the parameter configuration interface without saving the parameters .

Among them, the data bit and stop bit cannot be set. After the DHCP mode is turned on, the local IP address, gateway, and subnet mask cannot be configured and are only assigned by the router;

4.8.4. Screen Sleep

The device screen has a sleep function, which is off by default and can be set to on in the configuration interface.

In any interface, when there is no button operation for 180 seconds, the screen will enter the sleep mode. At this time, the interface displays Ebyte robot. Press any button can exit the sleep mode.

When the screen is in sleep mode, the running efficiency of device programs will be improved.

4.9 MODBUS parameter configuration

Note: According to the usage requirements, some software (such as KingView) requires adding +1 when converting from hexadecimal to decimal in order to operate on registers (all decimal values in the table have already been adjusted by +1).

4.9.1. DI Register List

Register function	Register address (HEX)	Register address (DEC)	Register type	Number	Operate	Data Range/Remarks	Related function code
DI status	0x0000	1-0001	Discrete Input	2	R	Input Port Status	R：0x02
DI filtering parameters	0x04B1	4-1202	Holding register	1	RW	Digital filtering parameters, ranging from 1 to 16. The smaller the number, the more sensitive it is, and the larger it is, the more stable it is. The default is 6	R：0x03 W：0x06、0x10
DI pulse count value	0x09DF	4-2528	Holding register	2	RW	Enter count value	R：0x03 W：0x06、0x10
DI reset method	0x0A43	4-2628	Holding register	2	RW	0x0000 automatic reset 0x0001 Manual reset	R：0x03 W：0x06、0x10
DI manual reset signal	0xAA7	4-2728	Holding register	2	RW	The reset method is manual, and the register writes 1 to clear the count value	R：0x03 W：0x06、0x10
DI counting method	0x0B0C	4-2829	Holding register	2	RW	Set the counting method for DI	R：0x03 W：0x06、0x10

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4.9.2. List of AI Registers

Register function	Register address (HEX)	Register address (DEC)	Register type	Number	Operate	Data Range/Remarks	Related function code
AI engineering quantity integer value	0x0064	3-0101	Input register	2	R	16 bit integer type, unit uA	R：0x04
AI engineering quantity floating point value	0x00C8	3-0201	Input register	4	R	32-bit floating-point type in mA	R：0x04
AI filtering parameters	0x04B0	4-1201	Holding register	1	RW	Analog input filtering parameters, range 1-16, smaller numbers are more sensitive, larger numbers are more stable, default 6	R：0x03 W：0x06、0x10
AI sampling range	0x04B2	4-1203	Holding register	2	RW	AI channel sampling range 0x0000: 0-20 mA 0x0001: 4-20mA	R：0x03 W：0x06、0x10
AI trigger high value	0x1F40	4-8001	Holding register	2	RW	0-20000(uA)	R：0x03 W：0x06、0x10
AI trigger low value	0x1F72	4-8051	Holding register	2	RW	0-20000(uA)	R：0x03 W：0x06、0x10
AI trigger mode	0x1FA4	4-8101	Holding register	2	RW	0, do not trigger 1. Rise trigger 2. Descending trigger 3. Bilateral triggering	R：0x03 W：0x06、0x10

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4.9.3. List of DO Registers

Register function	Register address (HEX)	Register address (DEC)	Register type	Number	Operate	Data Range/Remarks	Related function code
DO status	0x0000	0-0001	Coil	4	RW	Write to change the current DO state, read to obtain the current DO state	R：0x01 W：0x0F、0x05
State when DO is powered on	0x0064	4-0101	Holding register	4	RW	The default state of the coil after power on	R：0x01 W：0x0F、0x05
DO working mode	0x0578	4-1401	Holding register	4	RW	0x0000 level no follow mode 0x0001 Pulse no follow mode 0x0002 Follow mode 0x0003 Reverse Follow Mode 0x0004 Trigger Flip Mode	R：0x03 W：0x06、0x10
DO pulse width	0x05DC	4-1501	Holding register	4	RW	Range: 50-65535ms	R：0x03 W：0x06、0x10
DO Follow Source	DI:0x0000 AI:0x8000	DI:4-0001 AI:4-32769	Holding register	4	RW	Scope: 0x0000: Follow DI1 0x0001: Follow DI2 0x8000: Follow AI1 0x8001: Follow AI2	R：0x03 W：0x06、0x10

4.9.4. Module related registers

Register function	Register address (HEX)	Register Address (DEC)	Register type	Number	Operate	Data Range/Remarks	Related function code
Module address	0x07E8	4-2025	Holding register	1	RW	Modbus address, 1～247 configurable addresses	R：0x03 W：0x06

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Module model	0x07D0	4-2001	Holding register	12	R	Get the current model	R：0x03
Firmware version	0x07DC	4-2013	Holding register	1	R	Get firmware version number	R：0x03
Module name	0x07DE	4-2015	Holding register	10	RW	Custom module name	R：0x03 W：0x10
Module restart	0x07EA	4-2027	Holding register	1	W	Write 0x5BB5 to reboot.	W：0x06
Restore factory parameters	0x07E9	4-2026	Holding register	1	W	Write 0x5BB5 to restore factory settings.	W：0x06
Serial baud rate	0x0834	4-2101	Holding register	1	RW	See baud rate code table, Default is 9600 (0x0003)	R：0x03 W：0x06、0x10
Serial check digit	0x0836	4-2103	Holding register	1	RW	0x0000 no checksum (default) 0x0001 odd parity 0x0002 even parity	R：0x03 W：0x06、0x10

4.9.5. Network related registers

Register function	Register address (HEX)	Register address (DEC)	Register type	Number	Operate	Data Range/Remarks	Related function code
Module MAC address	0x0898	4-2201	Holding register	3	R	Device MAC parameters	R：0x03
Local IP address	0x089B	4-2204	Holding register	2	RW	Default: 192.168.3.7	R：0x03 W：0x06、0x10
local port	0x089D	4-2206	Holding register	1	RW	1～65535, default: 502	R：0x03 W：0x06、0x10
Subnet mask address	0x089E	4-2207	Holding register	2	RW	Default: 255.255.255.0	R：0x03 W：0x06、0x10
Gateway address	0x08A0	4-2209	Holding register	2	RW	Default: 192.168.3.1	R：0x03 W：0x06、0x10
DHCP mode setting	0x08A2	4-2211	Holding register	1	RW	0x0000 static IP (default) 0x0001 Obtain IP automatically	R：0x03 W：0x06、0x10
Target IP/domain name	0x08A3	4-2212	Holding register	64	RW	String format stored in IP/domain name Default IP: 192.168.3.3	R：0x03 W：0x06、0x10
Server port	0x08E3	4-2276	Holding register	1	RW	0-65535, default 502	R：0x03 W：0x06、0x10

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DNS server IP address	0x08E4	4-2277 ‘	Holding register	2	RW	Default 8.8.8.8	R：0x03 W：0x06、0x10
Module work mode	0x08E6	4-2279	Holding register	1	RW	0x0000 server mode 0x0001 client mode	R：0x03 W：0x06、0x10
Active upload	0x08E7	4-2280	Holding register	1	RW	0x0000 disabled, others: 1～65535s cycle sending	R：0x03 W：0x06、0x10
MOSBUS TCP/RTU conversion enable	0x08E8	4-2281	Holding register	1	RW	0, close, 1 open protocol conversion	R：0x03 W：0x06、0x10
MODBUS address filtering	0x08E9	4-2282	Holding register	1	RW	0: transparent transmission, 1-255: when the data is not local, check the slave address of th e command , and it can be passed when it is the set value	R：0x03 W：0x06、0x10

4.9.6. Examples of Modbus command operation instructions

1. Read coil (DO) status

Use the read coil state (01) function code to read the output coil state, for example:

01	01	00 00	00 04	3D C9
Modbus address	Function code	Register first address	Number of output coils read	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	01	01	01	90 48
Modbus address	Function code	Bytes of data	Returned status data	CRC check code

The status data 01 returned above indicates that the output DO1 is turned on.

2. Control coil (DO) state

Support operation of single coil (05), operation of multiple coils (0F) function code operation.

Use the 05 command to write a single command, for example:

01	05	00 00	FF 00	8C 3A
Modbus address	Function code	Register first address	Continuity: FF 00 Close: 00 00	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	05	00 00	FF 00	8C 3A

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Modbus address	Function code	Register first address	Operation method	CRC check code

The DO1 coil is turned on.

Use 0F function code as the command to write multiple coils, for example:

01	0F	00 00	00 04	01	0F	7E 92
Modbus address	Function code	Initial address	Number of coils	Bytes of data	Control coil data	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	0F	00 00	OO O4	54 08
Modbus address	Function code	Register address	Number of coils	CRC check code

The coils are all on.

3. Read the holding register

Use 03 function code to read one or more register values, for example:

01	03	05 78	00 01	04 DF
Modbus address	Function code	Register first address	Number of registers read	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	03	02	00 00	B8 44
Modbus address	Function code	Bytes of data	Returned data	CRC check code

The above 00 00 means that DO1 is in level output mode.

4. Operation holding register

Support operation of single register (06), operation of multiple registers (10) function code operation.

Use 06 function code to write a single holding register, for example: set the working mode of DO1 to pulse mode:

01	06	05 78	00 01	C8 DF
Modbus address	Function code	Register address	Write value	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

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01	06	05 78	00 01	C8 DF
Modbus address	Function code	Register address	Write value	CRC check code

If the modification is successful, the data in the 0x0578 register is 0x0001, and the pulse output mode is turned on.

Use function code 10 to write multiple holding register commands, for example: set the working mode of DO1 and DO2 at the same time.

01	10	05 78	00 02	04	00 01 00 01	5A 7D
Modbus address	Function code	Register head address	Number of registers	Number of bytes of written data	Written data	CRC check code

After sending the above command to the device through the 485 bus, the device will return the following values:

01	10	05 78	00 02	C1 1D
Modbus address	Function code	Register address	Number of registers	CRC check code

If the modification is successful, the values of the two consecutive registers starting with 0x0578 are 0x0001 and 0x0001 respectively, marking DO1 and DO2 to enable pulse output.

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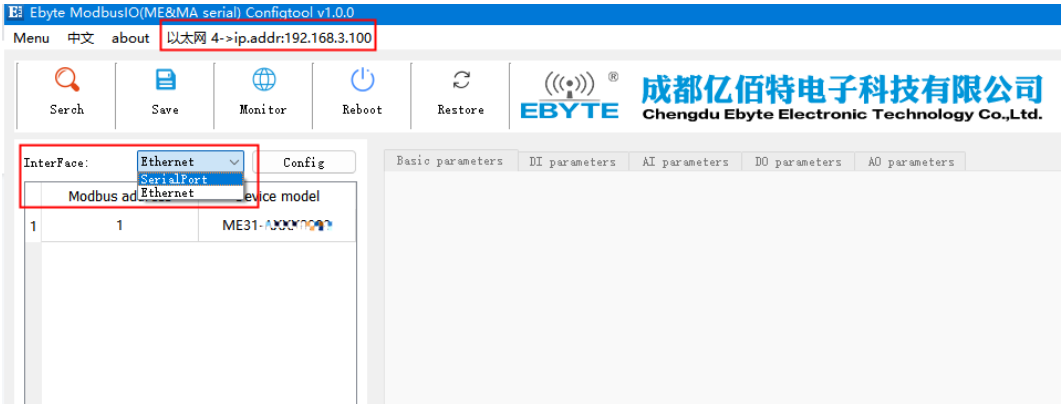
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V. Configuration Software

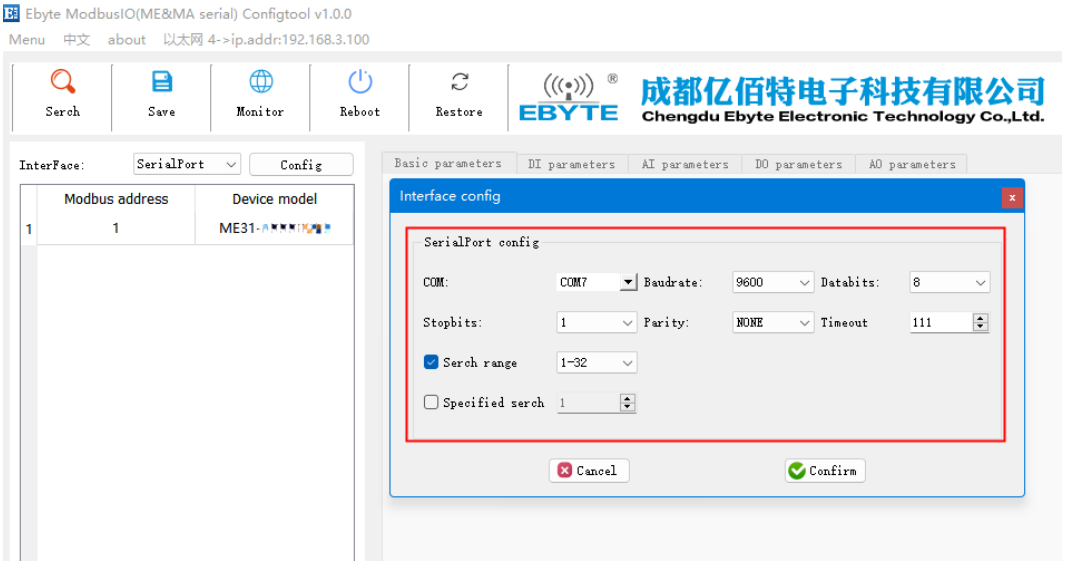
5.1. Acquisition and Control

Step 1: Connect the device to the configuration software.

（1）You can configure the device by selecting the interface (serial port/network port); if you choose the network port, you must first select the network card and then search for the device.



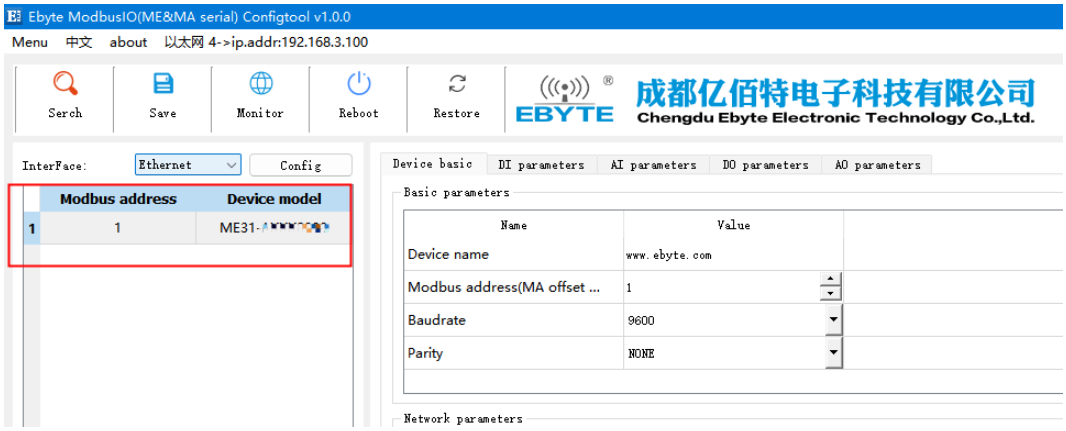
（2）If you choose a serial port, you need to select the corresponding serial port number, and the same baud rate, data bit, stop bit, parity bit and address segment search range as the device, and then search.



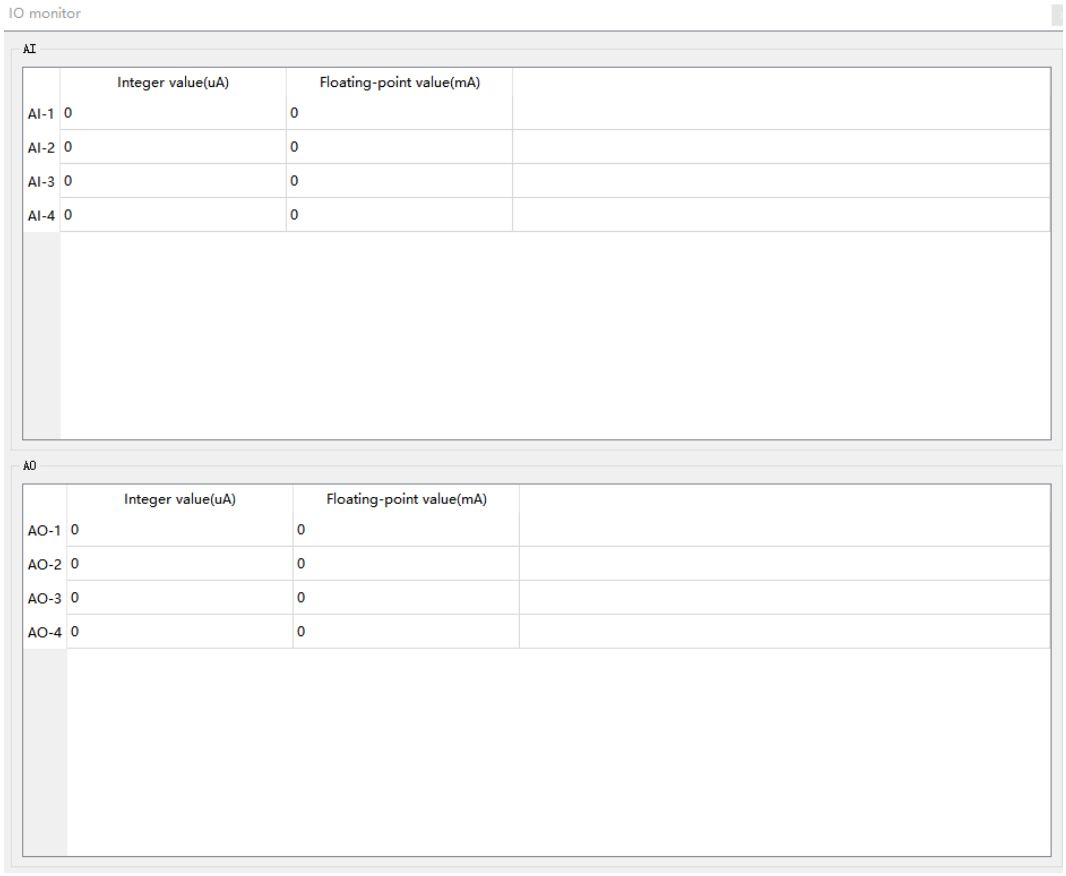
Step 2: Select the corresponding device.

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Step 3: Click the device online to enter the IO monitoring. The following is the IO monitoring screen display.



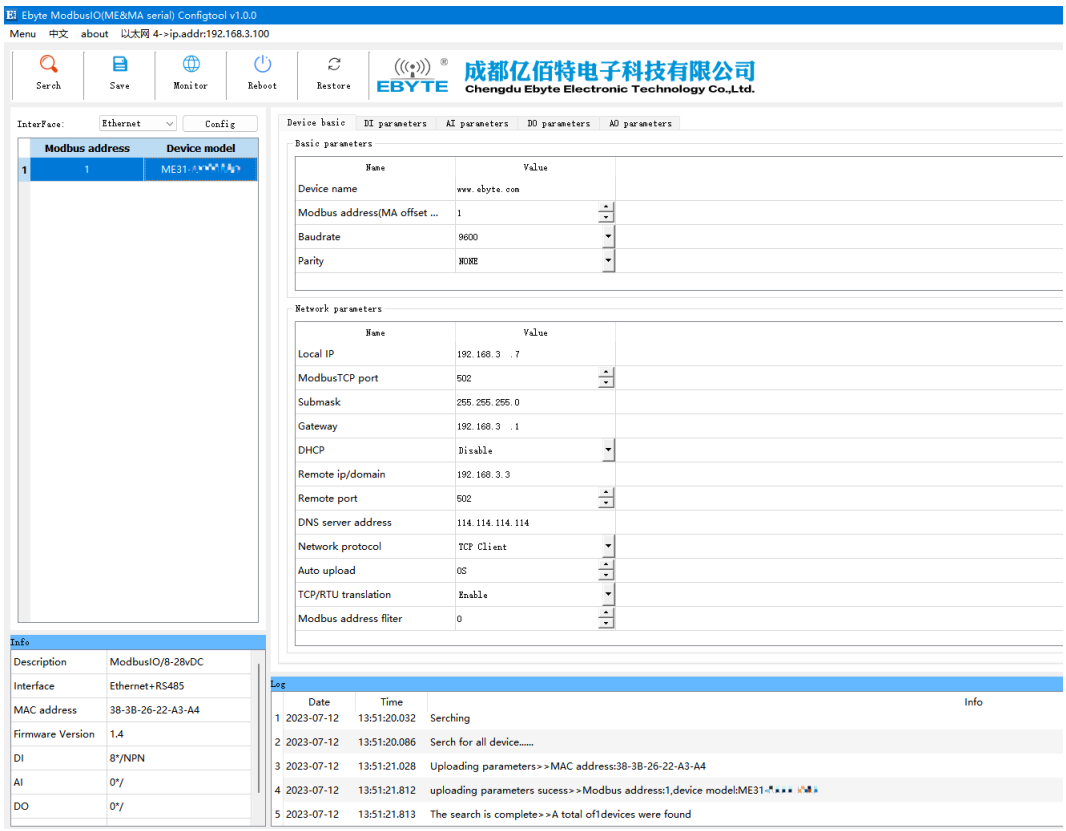
5.2. Parameter configuration interface

Step 1: Connect the device refer to "Acquisition and Control".

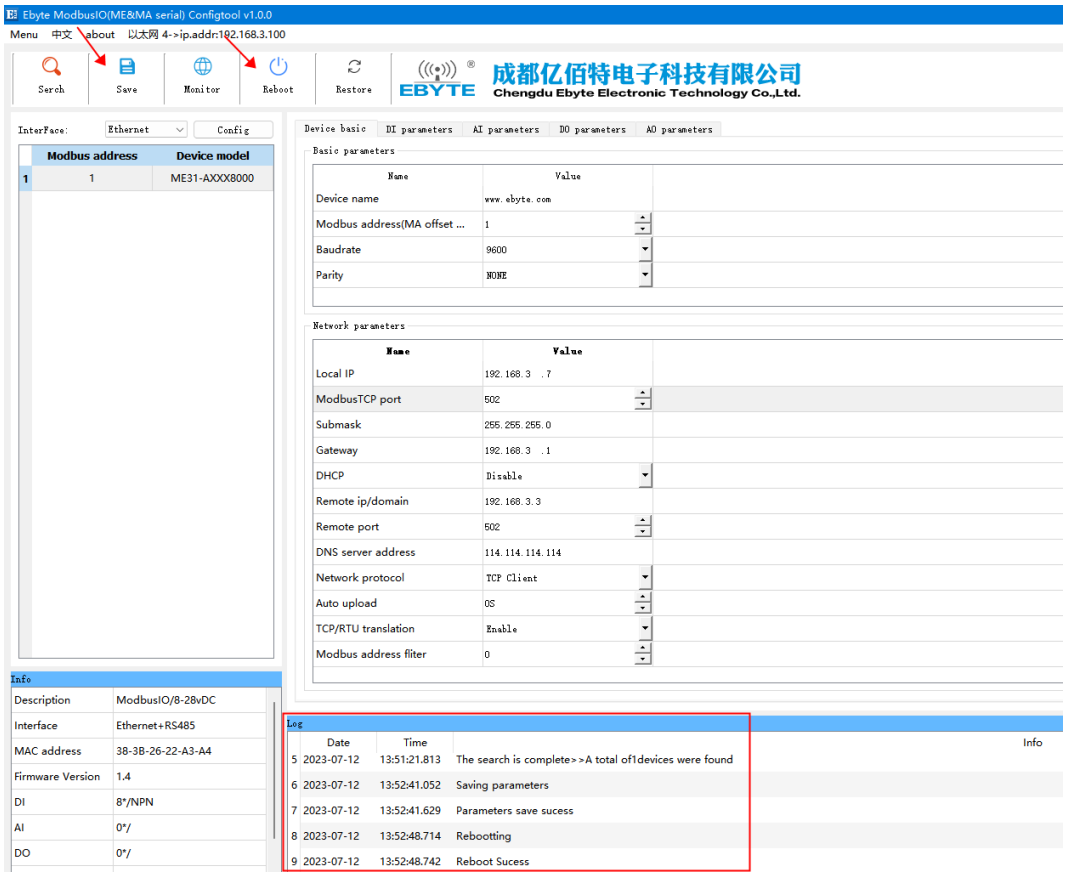
Step 2: You can configure device parameters, network parameters, DI parameters, AI parameters, DO parameters, and AO parameters (for example: if the device has no AO function, the AO parameters cannot be configured)

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Step 3: After configuring the parameters, click Download Parameters. After the prompt message in the log output shows that the parameters are saved successfully, click Restart the device. After the device restarts, the modified parameters will take effect.



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Revise history

Version	Revision date	Revision Notes	Maintenance man
1 .5	2 02 3-6-6	New version	LT
1.6	2024-10-18	Content revision	LT

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